

Consolidated Conformance Monitoring System Requirements

Document information

Project Title Precision Conformance Monitoring

Project Number 10.04.02
Project Manager Leonardo

Deliverable Name Consolidated Conformance Monitoring System Requirements

Deliverable ID D44
Edition 00.04.00
Template Version 03.00.00

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Abstract

This document includes the technical requirements for the Phase 2 and the Phase 3 functionalities to be provided by project P10.04.02. This document represents an update of P10.04.02 D08; in particular it includes the references, traceability and requirements adjustments from SJU and external reviewers on D08, the alignment with the architecture description delivered by 10.01.07 D120 (TAD) and the enhancement applied in consideration of the TMA operations deliverables (05.07.02: D77 preliminary V2 OSED for Step 1, D78 preliminary V2 SPR for Step 1 and D79 preliminary V2 INTEROP for Step 1), the En-route operations (04.07.02: D28 OSED_4 and D23 SPR MTCD 4) and Free route operation(04.07.02: D37 and D63).

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Rational for rejection

None.

8 Document History

Edition	Date	Status	Author	Justification
00.00.01	12/08/2016	Draft	BELGOCONTROL /DSNA	Initial version, based on D008
00.00.02	02/09/2016	Draft	LEONARDO	Updated version for internal review
00.00.03	09/09/2016	Draft	LEONARDO	Updated version for internal and external review
00.01.00	21/09/2016	Final	LEONARDO	Version for hand-over
00.02.00	25/10/2016	Final	LEONARDO	Version updated after SJU assessment
00.03.00	01/11/2016	Final	LEONARDO	Version updated after operational and technical projects review
00.04.00	10/11/2016	Final	LEONARDO	Version updated after SJU assessment

9 Intellectual Property Rights (foreground)

10 This deliverable consists of SJU foreground.

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Executive summary

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119 120 This Technical Specification (TS) document contains the final technical requirements for the Precision Conformance Monitoring to be provided by project P10.04.02 for SESAR Step 1. The document represents the deliverable D044 Conformance Monitoring System Requirements Phase 3. This document includes:

- the refinement of technical requirements depicted in the deliverable 10.04.02 D08 Conformance Monitoring Requirements Phase 3 on the base of further clarification received from other SESAR projects (like P05.07.02);
- some improvements related to enablers traceability:
- traceability and requirements adjustments and enhancement applied in consideration of the final SPR [7] and OSED [8] provided by P04.07.02;
- traceability and requirements adjustments and enhancements applied in consideration of the final OSED [11], SPR [12] and INTEROP [13] provided by P05.07.02.
- traceability and requirements adjustment and enhancement applied taking into account the OSED [9] and SPR [10] provided by P04.07.02 for Free Route environment

To summarize, in comparison with the previous TS document (D08)

- For P04.07.02 OSED/SPR and P05.07.02 OSED/SPR/INTEROP already covered by D08 TS requirements, traceability was updated;
- Some requirements were added from scratch to fully cover the P04.07.02 OSED/SPR and P05.07.02 OSED/SPR/INTEROP allocated to MONA;
- Some requirements were added to cover OSED/SPR provided by P04.07.02 for free route operations



1 Introduction

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- This Technical Specification document contains the requirements under which Monitoring Aids
- 123 functional block has to perform.
- The operational contributions considered for this TS document are P04.07.02 and P05.07.02 inputs.
- The P04.07.02 is an operational project dealing with "Separation Task in En Route Trajectory based
- 127 environment". The P05.07.02 instead is an operational project dealing with "Development of 4D
- 128 Trajectory-Based Operations for separation management using RNAV/PRNAV" focusing also on
- introduction of MTCD-based tools in TMA airspace.
- 130 Consequently this TS document covers both En-Route (including Free routing aspects) and TMA
- 131 trajectory based environment requirements.

1.1 Purpose of the document

- 133 This Technical Specification (TS) document contains system requirements for the Conformance
- 134 Monitoring for the SESAR Step 1 capability in TMA, En-Route and Free Route Environment. The
- 135 relationship between the TS document and the other SESAR documents is illustrated in Figure 1.

Figure 1: TS document with regards to the other SESAR deliverables

In support of the generation of the 10.04.02 Step 3 functional requirements, operational input was received from the P04.07.02 and P05.07.02 projects. The P10.04.02 project received the deliverables of the Operational Service and Environment Definition (OSED) [8] [9] [11], Safety and Performance Requirements (SPR) [7] [10] [12] and Interoperability Requirements INTEROP [13] for review/comments and implementation. The technical requirements presented in Chapter 3 of this document have been obtained directly from those OSED, SPR and INTEROP.

The 04.07.02 OSED describes a concept of operations made up by the following three services with different maturity levels (see [8] for detailed maturity):

- TRajectory Adjustment through Constraint of Time (TRACT)
- Conflict Detection and Resolution Aid to Planning Controller (CD&R aid to PC)
- Conflict Detection and Resolution Aid to Tactical Controller (CD&R aid to TC)

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- 149 The 04.07.02 OSED also specifies operational concepts dealing with:
- 150 Monitoring vertical rate
- Monitoring Mode-S parameters against clearances 151
- Aspects relating to tactical and deviation trajectories 152
- 153 The 04.07.02 SPR documents describe the derived safety objectives and associated requirements for
- the two, out of the three, services within project P04.07.02. The two services are: CD/R aid to PC and 154
- CD/R aid to TC. It is expected that these requirements will form an input to the later stages of the 155
- 156 project and to support the growing maturity of these services.
- 157 Direct routing (for flights both in cruise and vertically evolving for cross ACC borders and in high &
- 158 very high complexity environments) and Free routing (for Flights both in cruise and vertically evolving
- within low to medium complexity environments) aspects are specified in OSED [9] and SPR [10] 159
- 160 provided by P04.07.02
- The 05.07.02 OSED document details the Preliminary (V2) Operational Concept for Step 1 161
- Separation Management in TMA. It also includes the "Collaborative Control" thread of the project 162
- P05.07.03 that focuses on Controller Team Organisation; specifically Roles and Responsibilities 163
- within a Trajectory Based Operation within TMA Airspace. 164
- 165 The 05.07.02 SPR document provides the Safety and Performance Requirements for the Medium
- 166 Density/Medium Complexity and High Density/High Complexity operational environments, related to
- 167 the operational Services defined in the SESAR project 05.07.02 OSED document. It also includes a
- 168 summary of the Safety Assessment from which these requirements have been derived.
- The 05.07.02 INTEROP document provides the Interoperability Requirements for air traffic services 169
- 170 (ATS) supported by data communications for SESAR Step 1 Separation Management in TMA. This
- version is based on the OSED V2 and considers the results of the validation exercises (EXE-171
- 05.07.02-VP-738, EXE-05.07.02-VP-740, EXE-05.07.02-VP-741 and EXE-05.07.02-VP-743). 172
- 173 The architecture required for Conformance Monitoring makes up high-level functional block
- 174 "MONitoring Aids" from P10.01.07 deliverable D120 "Technical Architecture Description (TAD) - Cycle
- 2015" [6]. In this TS document, the functionality is further broken down into the following functional 175
- 176
- sub-blocks called "Eligibility", "Lateral Conformance Monitoring", "Vertical Rate Conformance Monitoring", " CFL Conformance Monitoring", " Level Bust", "NoTT Monitoring", "Potential 177
- Coordination Failure", "Mode-S DAP Conformance", "SID and STAR Constraints", Conformance 178
- Monitoring related to Aircraft derived data" as illustrated by Figure 4. 179

1.2 Intended readership

- The intended readership includes: 181
- All the operational projects linked to the 10.04.02 project (including P04.07.02, P05.07.02 and 182 P05.07.03) for coordination and validation purposes; 183
- Project in charge to perform validation across several concept functions/elements of En 184 Route operating context (P04.03); 185
 - The ATC System Specification project (P10.01.07);
- 187 • Other WP10 projects for information and coordination purposes, including:

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- P10.02.01 (The trajectory data are required inputs into the Conformance Monitoring requirements defined in section 3 of this document, hence a common understanding between the two projects is essential in order to achieve both a well-defined ground system concept and a functioning prototype.);
- P10.04.01 (The implementation of Conformance Monitoring requirements in section 3 are dependent from the CD&R requirements, a shared awareness between the two projects ensures that the functionality complements each other as intended.);
- P10.10.02 (Closed) and 10.10.03 (HMI requirements related to the P10.04 02 scope have been included in previous TS document).
- Internal project members.

1.3 Inputs from other projects

- The requirement set in this Technical Specification consists of the requirements specified in P10.04.02 D08 ([5]) updated and aligned to 04.07.02 OSED/SPR ([7], [8], [9], [10]) and 05.07.02
- OSED/SPR/INTEROP ([11], [12], [13]) needed to support Phase 2 and Phase 3 functionalities.
- 202 Another input for this document is D120 Technical Architecture Description (TAD) Cycle 2015
- provided by P10.01.07 [6]; indeed, the architecture required for Conformance Monitoring has been
- 204 derived from MONitoring Aids Functional Block depicted in this Technical Architecture Description
- 205 document.

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1.4 Structure of the document

- 207 This document is structured as follows:
- 208 Chapter 1: Introduction
- 209 Chapter 2: General Functional Block Description
- 210 Chapter 3: Functional block Functional and non-Functional Requirements
- 211 Chapter 4: Assumptions
- 212 Chapter 5: References
- 213 Appendix A: Traceability of TS requirements with P04.07.02 OSED/SPR and P05.07.02
- 214 OSED/SPR/INTEROP
- 215 Appendix B: Subset of TS requirements linked to HMI functional block
- 216 Appendix C: Subset of 04.07.02 OSED and SPR allocated to Functional Block MONA by P10.01.07
- 217 Appendix D: Subset of P05.07.02 OSED, SPR and INTEROP allocated to Functional Block MONA by
- 218 P10.04.02 partners
- 219 Appendix E: Traceability of TS requirements to SESAR Solutions
- 220 Appendix F: Description of new functionalities developed in the top of FASTI baseline

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1.5 Requirements Definitions – General Guidance

222 All the requirements are provided in Chapter 3 of the document. The main sections are structured in accordance with the SESAR TS Template ([1],[3]) and the Requirements and V&V Guidelines 223 224 provided by SJU ([2]):

225 Section 3.1: Capabilities

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Section 3.2: Adaptability 226

Section 3.3: Performance Characteristics

228 Section 3.4: Safety & Security 229 Section 3.5: Maintainability

230 Section 3.6: Reliability

231 Section 3.7: Functional block Internal Data Requirements

232 Section 3.8: Design and Construction Constraints 233

Section 3.9: Functional block Interface Requirements

The key functional requirements for Conformance Monitoring are provided in "Capabilities" section 3.1 structured as following:

Section 3.1: Capabilities

Section 3.1.1: Functional Requirements

Section 3.1.1.1: Eligibility Requirements

239 Section 3.1.1.2: Lateral Conformance Requirements 240 Section 3.1.1.3: Vertical Rate Conformance Requirements

Section 3.1.1.4: CFL Conformance Requirements

Section 3.1.1.5: Level Bust Requirements

243 Section 3.1.1.6: NoTT Conformance Requirements

Section 3.1.1.7: Potential Coordination Failure Requirements

Section 3.1.1.8: Mode-S DAP Conformance Requirements

Section 3.1.1.9: SID and STAR constraints conformance requirements

Section 3.1.1.10: Conformance monitoring requirements related Aircraft Derived Data Interface requirements are provided in "Functional block Interface Requirements" section 3.9

249 structured as following:

250 Section 3.9: Functional block interface requirements

Section 3.9.1 System Interface Requirements

Section 3.9.1.1: Surveillance Interface Requirements Section 3.9.1.2: Output Interface Requirements Section 3.9.1.3: Input Interface Requirements

255 Section 3.9.2: HMI Requirements

As shown above, very general HMI requirements related to MONitoring Aids have been introduced a 256 dedicated section that was included in the Functional Block Interface Requirements... 257

Each requirement related to MONitoring Aids Functional Block has been numbered according to the 258 following template: 259

<Object type>-<Project code>-<Document code>-<Reference code>.<Reference number>

REQ-10.04.02-TS-nnnn.uuuu e.g.

REQ is the <Object type> (i.e. requirement),

10.04.02 is the <Project code>,

TS is the <Document code> (i.e. technical specification), 0

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- 265 o nnnn is the <Reference code>, sequence of 4 alphanumeric characters, 266
 - Requirements from Phase 1 contain 0 in the first digit of the reference code
 - REQ-10.04.02-TS-**0**nnn.uuuu
 - Requirements from Phase 2 contain 2 in the first digit of the reference code
 - REQ-10.04.02-TS-2nnn.uuuu
 - Requirements from Phase 3 contain 3 in the first digit of the reference code
- REQ-10.04.02-TS-3nnn.uuuu 271

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- 272 o uuuu is the <Reference number>, sequence of 4 digits,
 - Requirements use the following recommended layout

Identifier	
Requirement	
Title	
Status	
Rationale	
Category	
Validation Method	
Verification Method	

Relationship	Linked Element Type	Identifier	Compliance
<satisfies></satisfies>	<enabler></enabler>	Enabler code	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	INTEROP or SPR Requirement Identifier	<full></full>
<allocated to=""></allocated>	<functional block=""></functional>	Functional block Identifier	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	Operational Focus Area Identifier	N/A
<changed_because_of></changed_because_of>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	Project Identifier	N/A

Table 1: Requirements layout

1.6 Functional block Purpose

The MONitoring Aids functional block, which is the topic of this TS, includes a number of conformance monitoring checks whose aim is improve flight adherence to planned trajectory.

The enablers for the requirements in this technical specification are primarily based on the relevant Operational Improvements from the 04.07.02 OSED/SPR ([7], [8], [9], [10]) OSED/SPR/INTEROP ([11], [12], [13]), which are based on the Dataset 16 [4]. The enablers are summarized in the following table:

Relevant Operational Improvement	Enabler
CM-0205: Conflict Detection and Resolution	ER_ATC_157:

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in En-Route using trajectory data in Predefined and User Preferred Routes environments	ATC System Support for Medium-Term Conflict Detection and Resolution in Enroute Airspace
CM-0207-A: Automated Ground Based Flight Conformance Monitoring in En Route in Step 1	ER_ATC_91: ATC System Support for Advanced Conformance Monitoring in En Route Airspace ¹
CM-0208-A Automated Flight Conformance Monitoring in the TMA in Step 1	APP_ATC_94: ATC tools in support of RNP (e.g. RNP1, A-RNP, RNP APCH, etc) for Approach/TMA

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Table 2: Summary of Enablers for Conformance Monitoring

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CM-0205 and CM-0207-A have been split in Dataset 16 [4] under the leadership of P04.02.

The scope of CM-0205 is now limited to what was validated in SESAR1, so will reach V3 in release 5. The corresponding enabler is ER_ATC_157. A new OI, CM-0209, was created for the part being transferred to SESAR 2020.

Similarly, CM-0207-A is also limited to the SESAR 1 scope, and will also reach V3 as a result of the release 5 exercises. Its enabler is ER_ATC_91 (new), which P10.04.02 technical specification will be linked to. The SESAR 2020 part is in a new OI, CM-0210, which is linked to enabler ER ATC 94. The new enabler ER_ATC_91 is just monitoring aids, and P10.04.02 technical specification for SESAR 1 will link to it. This means changing the link from ER ATC 94.

The scope of CM-0208-A is also in the SESAR2020 scope. Its enabler is APP_ATC_94 which addresses the functionality required in Approach/TMA; the ER ATC 94 is for the corresponding Enroute enhancement. The rationale for creating separate enablers is to accommodate the different timescales for the development of requirements in the two environments.

307 The Monitoring Aids functional block encompasses the following functions:

- 308 Flight Trajectory deviation and conformance monitoring,
- 309 Tactical Instruction and Clearance conformance monitoring,
- 310 Flight progress monitoring and update,
 - Reminder tools: reminder of instructions to be issued,
- 312 Direct and Free Routing monitoring.

The trajectory prediction, included in P04.07.02 OSED/SPR and similarly in P05.07.02 OSED/SPR/INTEROP, are not in scope for this TS document. The computation of trajectories is addressed by SESAR project 10.02.01 and will be available to the MONitoring Aid block as inputs from the Trajectory Prediction & Management functional block. The Conflict Management is addressed by SESAR project 10.04.01.

The MONA functional block does not include the actual HMI or displays either. Hence the detailed visualization requirements are not in the 10.04.02 scope. Anyway some general HMI requirements

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¹ ER_ATC_91 is the new enabler defined under the leadership of 10.01.07 and linked to CM-0207-A. In this document the traceability will be modified by tracing the TS requirements to this new enabler.

were included in this TS. Project 10.10.2 reviewed the general HMI requirements included in section 3.9.2 and provided some additional HMI requirements included in the section 3.9.2 as well. The HMI prototypes will be developed based on these closely coordinated requirements.

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1.7 Functional block Overview

This Technical Specification describes the ER/APP functional block "Monitoring Aids" that is included in the high level illustration from the Technical Architecture Description - Cycle 2015 [6] and that has been reproduced in the figure below.

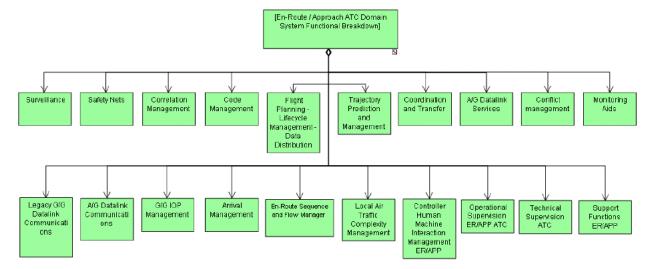


Figure 2: Functional Block Tree Diagram from EATMA

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The main purpose of this functional block is to provide MONitoring Aids (MONA) assistance to the ATCO(s).

In particular, Monitoring Aids encompasses the following functions:

- Flight Trajectory deviation and conformance monitoring,
- Tactical Instruction and Clearance conformance monitoring,
- Flight progress monitoring and update,
- 337 Reminder tools,
- 338 Direct and Free Routing monitoring.

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The Monitoring Aids will support ATCOs to detect and minimize trajectory non-conformances.

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1.8 Glossary of terms

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Term	Definition	Source
Correlation period	LUDGATE	10.01.07.D120 ATC System Specification

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Term	Definition	Source
Correlated flight	Flight plan with a planned trajectory correlated with a radar track	10.01.07.D120 ATC System Specification
External Sector	A sector outside of the airspace of responsibility assigned to the subject ATM system.	FASTI program
Internal Sector	A sector inside of the airspace of responsibility assigned to the subject ATM system.	FASTI program
Route	The 2D trajectory of an aircraft, expressed as significant points, ATS routes or geographical points.	EATM Glossary
Sector	A part of airspace controlled by a team of controllers, defined, notably, by its geographical co-ordinates and its assigned radio frequency	EATM Glossary
State Vector	A vector describing the state of an object in terms of its position co- ordinates, ground speed, course, accelerations and mode-of-flight	EATM Glossary
System Track	A generic entity representing the surveillance data as transmitted by the surveillance system	EATM Glossary
Trajectory and Fligh	t Related Terms	
Trajectory	The predicted behaviour of an aircraft.	4.7.2. D28
	Note: the Trajectory is usually modelled as a set of consecutive segments linking waypoints and/or points computed by the aircraft avionics (e.g. FMS) or by the ground system to build the vertical profile and the lateral transitions.	OSED Glossary
	Note: Each point is defined by a longitude, latitude, a vertical distance and a time.	
Tentative Trajectory	Tentative trajectories are created from another trajectory that is in operational use (Tactical, Planning or otherwise). They reflect tentative what-if flight data selected by the controller. If these conditions are then committed the Tentative trajectory and the associated data will be used to establish the new operational trajectory. If the conditions are discarded then it will also be discarded.	4.7.2. D28 OSED Glossary
	Note: Tentative trajectories support What-If probing and are created during this process.	
Speculative Trajectory	A Trajectory that uses flight data other than those currently committed or tentatively selected (during a What-If Probing operation), by the controller.	4.7.2. D28OSED Glossary
	Note: Speculative Trajectories are produced for the purpose of What- Else probing.	
Tactical Trajectory	The Tactical Trajectory is calculated within a short look-ahead time (e.g. up to 15 minutes) during tactical ATC operations (sector planning layer). It therefore reflects an accurate view of the predicted flight evolution, starting from the current flight position (generally, as reported by surveillance), with low uncertainty and high precision. It is kept up to date with all clearances, including tactical instructions. During any open tactical manoeuvres it will also be reflecting those temporary conditions.	4.7.2. D28 OSED Glossary
	It is usually determined with a fast update rate (e.g. 5 seconds) and with an optimised Uncertainty calculation; to maximise response and minimise the incidence of false warnings.	
	Note: The Tactical Trajectory supports the tactical ATC operations when the flight follows its normal behaviour	
[Tactical/Planning] Deviation Trajectory	The Deviation Trajectory provides the predicted profile of the aircraft based on the observed behaviour, extrapolated from the particular deviation from the current clearance (or deviation from coordination	4.7.2. D28 OSED Glossary

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Term	Definition	Source
	constraint for Planning Deviation Trajectories).	
	Note: Deviation Trajectories are necessary for situations where non- compliance with a flight's expected tactical or coordinated behaviour is observed, with respect to an applicable tolerance threshold.	
	Deviation Trajectories support Tactical/Planner ATC operations when the flight has deviated from its predicted behaviour.	
	The Tactical Deviation Trajectory is useful for a short prediction horizon (e.g. 3-5 minutes).	
	A Planning Deviation Trajectory follows the cleared route of the flight, irrespective of any coordination constraints (as the flight has been observed to be deviating from these constraints).	
	During periods where a Deviation Trajectory is necessary it may also be used by TC/PC CD&R Aid.	
Subject Flight	A flight that has been explicitly selected by the Controller concerned.	4.7.2. D28 OSED Glossary
Subject Trajectory	The Trajectory of the Subject Flight	4.7.2. D28 OSED Glossary
Environmental Flight	A flight of interest to the Controller which is not the Subject Flight. The Subject Flight will be checked for encounters with all Environmental Flights.	4.7.2. D28 OSED Glossary
Context Flight	A flight that may need to be considered by the Planner ATCO when making coordination choices for the Subject Flight, due to the flights' anticipated vertical and lateral profiles.	4.7.2. D28 OSED Glossary
	Context Flights are those Environmental Flights that are involved in a Planning Context Encounter with the Subject Flight.	
	Note: Context Flights may not currently be involved in a Planning Encounter based on their current clearance or existing coordinated levels.	
Environment Trajectory	The Trajectory of an Environmental Flight	4.7.2. D28 OSED Glossary
Context Trajectory	Context Trajectories represent the expected utilisation of airspace by each flight. Context Trajectories are built for the Subject Flight and Environmental Flights.	4.7.2. D28 OSED Glossary
	Note: Context Trajectories are similar to Coordination Trajectories. Each Context Trajectory maintains a single level and follows the lateral profile of the Planned Trajectory. Context Trajectories are built at every standard Flight Level from the entry-context level to the exit-context level. The identification of entry-context and exit-context levels is dictated by the information available in the system at the time of the probe. They represent the lowest and highest level at which the flight is anticipated to occupy in the sector.	
	The Origin and Termination points on Context Trajectories depend on whether the flight is the Subject flight or an Environmental flight and on the flight's anticipated vertical profile.	
	Example of Subject Flight Context Trajectories:	
	exit-context intermediate context trajectories	
	SECTOR 1 SECTOR 2 entry-context SECTOR 3	
	Example of Environmental Flight Context Trajectories:	

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User Preferred Route A preferred route that is provided by an Airspace User during the flight planning and agreement phase. In Step 1 it may take advantage from Free Route Airspace (FRA) for optimum routings. Note: A User Preferred Route may include published as well as non-	Term	Definition	Source
Route planning and agreement phase. In Step 1 it may take advantage from Free Route Airspace (FRA) for optimum routings.		intermediate context trajectories entry-context	
Note: A User Preferred Route may include published as well as non-		planning and agreement phase. In Step 1 it may take advantage from	4.7.2. D28 OSED Glossary
published points defined in latitude/longitude or point bearing/distance. Such waypoints are inserted in the FMS for trajectory computation		published points defined in latitude/longitude or point bearing/distance.	

Planning Trajectory Related Terms

Since the needs of the PC and TC differ in many respects, the trajectories produced to support the planning and tactical roles are different.

Planning Trajectories are used to predict encounters between flights that are of concern to the PC. They take account of the original flight plan, modified by agreed co-ordination constraints and standing agreements, but possibly unconstrained by tactical instructions.

possibly diffeonstrained by factical instructions.		
Planned Trajectory	The Planned Trajectory represents the stable medium to long term behaviour of the aircraft but may be inaccurate over the short term where tactical instructions that will be issued to achieve the longer term plan are not yet known.	4.7.2. D28 OSED Glossary
	It takes into account the planned route and requested vertical profile, strategic ATC constraints, Closed Loop Instructions/Clearances, coordination conditions and the current state of the aircraft. Assumptions may be made to close Open Loop Instructions/Clearances issued by tactical controllers.	
	It is calculated within the planning look-ahead timeframe, starting from the Area of Interest of the unit concerned, or the aircraft's current position (whichever is later).	
	It is constrained during all phases of flight by boundary crossing targets (e.g. standing agreements between the Units concerned).	
	Note: The Planned Trajectory supports the ATC planning operations. It is used primarily to support data distribution within the system and in the determination of the top of descent point. As such, uncertainty does not need to be calculated for this trajectory. It is also used as the starting point for derivation of more specific local ATC trajectories.	
Planned Sequence Trajectory	A Trajectory that is derived from the Planned Trajectory as it follows the vertical and lateral profile of the Planned Trajectory, truncated in time to an adaptable parameter (e.g. 25 minutes).	4.7.2. D28 OSED Glossary
	Uncertainty is added (although the lateral uncertainty may be zero).	
	Note: The Planned Sequence Trajectory is used for the determination of co-ordination levels and the sector penetration sequence.	
	It is used for both manual coordination and integrated coordination purposes and may be used by the CD&R Aid (with the Planning Separation) for traversals of the sector concerned (CD&R for entry and exit to the sector are covered by the Coordination Trajectory).	
[Entry/Exit] Coordination	A Trajectory that is derived from the Planned Sequence Trajectory. It follows the lateral profile of the Planned Sequence Trajectory2 but	4.7.2. D28 OSED Glossary

² It may be possible for the lateral profile of Coordination Trajectories to be altered from that of the Planning Trajectory to take into account relevant Coordination Constraints applied at the boundary between two sectors.



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Term	Definition	Source
Trajectory Or	maintains a specific coordination level relevant to the boundary between two sectors. It represents the expected behaviour of the aircraft according to the entry/exit co-ordination conditions.	
[Entry/Exit] Trajectory	Entry = A Trajectory that is built at levels associated with the sector entry coordination for the flight.	
	Exit = A Trajectory that is built at levels associated with the sector exit coordination for the flight.	
	Note: The Coordination Trajectory:	
	Supports both lateral and vertical boundary co-ordinations;	
	Can have the origin and end truncated (e.g. at sector boundaries);	
	Is necessary for predicting encounters with flights that are co-ordinated with the sector but not yet in communication with that sector.	
	Because it is only needed for boundary crossing conditions it can have a relatively short prediction horizon; typically up to the point where the flight is assumed by the sector concerned.	
TRACT Trajectory	A Trajectory that is derived from the Planned Trajectory. It is similar to the Planned Sequence Trajectory in that it follows the vertical and lateral profile of the Planned Trajectory, truncated in time to an adaptable parameter (which is suitable for the TRACT process) and uncertainty is included.	4.7.2. D28 OSED Glossary
	Note: It is used in support of the TRACT CD&R process.	
Initial Reference Business Trajectory (iRBT for Step 1)	The representation of an airspace user's intention with respect to a given flight, guaranteeing the best outcome for this flight (as seen from the airspace user's perspective), respecting momentary and permanent constraints.	4.7.2. D28 OSED Glossary
	The Reference Business Trajectory (RBT) refers to the Business Trajectory during the execution phase of the flight. It is the Business Trajectory which the airspace user agrees to fly and the Air Navigation Service Providers (ANSP) and Airports agree to facilitate (subject to separation provision)	
	Note: The iRBT is the Step 1 attempt to move towards the full SESAR Reference Business Trajectory. It is shared between the Step 1 SWIM subscribers and is updated from down-linked aircraft trajectory updates. The extent to which this update, synchronisation and sharing is possible within Step 1 will depend on progress made by enabling projects. Likewise the extent to which guarantees can be made concerning best outcome will be subject to the same Step 1 development progress and validation.	
Constraint and Target Related Terms		
СТО	An ATM imposed time constraint over a point.	4.7.2. D28 OSED
	Note: This constraint is sent by the ground system to the aircraft.	Glossary
CTA/RTA	An ATM imposed time constraint on a defined merging point associated with an arrival runway.	4.7.2. D28 OSED Glossary
	Note: This constraint is sent by the ground system to the aircraft.	
Active CTO/CTA/RTA	A CTO or CTA or RTA that is currently taken into account by both, the avionics (e.g. FMS) and the Ground Systems.	4.7.2. D28 OSED Glossary
	Note: It is considered to be active from the moment when both the air and the Ground Systems have taken it into account, until the application point of the constraint is over-flown or until it is cancelled in the Air and the Ground systems.	
Level Block	A level or a range of levels that is blocked off to other traffic, e.g. crossers	4.7.2. D28 OSED Glossary

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Term	Definition	Source
Target Time of Arrival	An Arrival Time which is not a constraint but a progressively refined planning time that is used to coordinate between arrival and departure management applications. It is an ATM computed time.	4.7.2. D28 OSED Glossary
Clearance and Instru	iction Related Terms	
Open loop Instruction/Clearance	An ATC clearance or instruction where a full trajectory extrapolation beyond the point or segment(s) affected is not possible using the normal prediction process, i.e. without special measures to assert a closure condition (e.g. time limit on headings and most probable point of return to original routing).	4.7.2. D28 OSED Glossary
	Open loop instructions/clearances can be cancelled by a Closed-loop instruction/clearance .	
	Note: Most tactical instructions/clearances take this form; they include heading (including track offset), level, and speed restrictions and exceptionally could also cover rates of climb or descent.	
Closed loop Instruction/Clearance	An ATC clearance or instruction where a full trajectory extrapolation beyond the point or segment(s) affected is possible using the normal prediction process.	4.7.2. D28 OSED Glossary
	Note: A typical example is a direct route from one point to another on the original route.	
NFL, SFL	The NFL is the cleared level that the aircraft will have when it will arrive in the sector. The NFL is given by the upstream sector. The NFL is equal to the TFL of the upstream sector.	4.7.2. D28 OSED Glossary
	The SFL is the second level that permits to determine the interval of flight levels in which the aircraft will arrive in the sector. So when arriving in the sector the aircraft will be between the SFL and the NFL.	

1.9 Acronyms and Terminology

Term	Definition
2D, 3D, 4D	Two Dimensional, Three Dimensional, Four Dimensional
4D TM	Four dimensional Trajectory Management
4DTRAD	Four Dimensional TRAjectory Data link
A/C	Aircraft
ACC	Area Control Centre
ADD	Architecture Definition Document
ADEP	Aerodrome of Departure
ADES	Aerodrome of Destination
ADS-B	Automatic Dependent Surveillance-Broadcast
ADS-C	Automatic Dependent Surveillance-Contract

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Term	Definition
AFL	Actual Flight Level
AMAN	Arrival MANager
ANSP	Air Navigation Service Provider
APP	Approach
АТС	Air Traffic Control
АТСО	Air Traffic Controller
ATIS	Automatic Terminal Information Service
АТМ	Air Traffic Management
ATS	Air Traffic Services
ATSU	Air Traffic Services Unit
CCD	Continuous Climb Departure
CDA	Continuous Descent Approach
CD	Conflict Detection
CD/R	Conflict Detection and Resolution
СДО	Continuous Descent Operations
CFL	Cleared (Current) Flight Level
СҒМИ	Central Flow Management Unit
СНМІ	Controller Human Machine Interface Management
CNS	Communications, Navigation and Surveillance
СОР	Coordination Point
CPDLC	Controller Pilot Data Link Communication
СТА	Control Time of Arrival
сто	Control Time Over
CWP	Controller Working Position
DAP	Downlink Aircraft Parameter
DER	Departure End of the Runway

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Term	Definition
DFS	Deutsche Flugsicherung GmbH (German ANSP)
DMAN	Departure MANager
DOD	Detailed Operational Description
DRA	Direct-Route Airspace
DSNA	Direction des Services de la Navigation Aérienne (Directorate Air Navigation Services) (French ANSP)
EATMA	European ATM Architecture
EPP	Extended Projected Profile
ER	En Route
ERATO	En Route Air Trafic Organizer
ETA	Estimated Time of Arrival
ETFMS	Enhanced Tactical Flow Management System
ЕТО	Estimated Time Over
EUROCAE	EURopean Organization for Civil Aviation Equipment
FASTI	First ATC Support Tools Implementation (programme)
FDMP	Flight Data Manager Publisher
FDPS	Flight Data Processing System
FIR	Flight Information Region
FIS	Flight Information Service
FL	Flight Level
FMS	Flight Management System
FP	Flight Plan
FRA	Free-Route Airspace
FTS	Fast Time Simulation
GA	General Aviation
GAT	General Air Traffic



Term	Definition
нмі	Human-Machine Interface
i4D TM	Initial 4-Dimensional (Trajectory Management)
IAS	Indicated Air Speed
IBP	Industry-Based Prototypes
ICAO	International Civil Aviation Organisation
IFR	Instrument Flight Rules
INTEROP	Interoperability Requirements
IOP	Interoperability
iRBT	Initial Reference Business Trajectory
IRS	Interface Requirements Specification
ITEC	Interoperability Through European Collaboration
MONA	MONitoring Aids
MSA	Minimum Sector Altitude
мѕР	Multi Sector Planning
MTCD	Medium-Term Conflict Detection
NATS	National Air Traffic Services (UK ANSP)
NFL	eNtry Flight Level
NoTT	No Tactical Trajectory
OAT	Operational Air Traffic
ОІ	Operational Improvement
OSED	Operational Service(s) Environmental Description
P04.07.02	Project 04.07.02. Separation Task in En Route Trajectory based environment
PC	Planning Controller
PIR	Project Initiation Report
RBT	Reference Business Trajectory
RNP	Required Navigation Performance

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Term	Definition
RTA	Requested Time of Arrival
RTS	Real Time Simulation
RVSM	Reduced Vertical Separation Minimum
SDPDS	Surveillance Data Processing and Distribution System
SESAR	Single European Sky ATM Research Programme
SFL	Supplementary Flight Level
SID	Standard Instrument Departure
SJU	SESAR Joint Undertaking (Agency of the European Commission)
SPR	Safety Performance Requirement
STAR	STandard instrument ARrival
SUR	Surveillance Data Processing and Distribution System
TAD	Technical Architecture Description
тс	Tactical Controller
TRACT	TRajectory Adjustment through Constraint of Time
тст	Tactical Controller Tool
ТМА	Terminal Manoeuvring Area
TOAC	Time Of Arrival Control
тос	Top Of Climb
TOD	Top Of Descent
TP	Trajectory Prediction
TP&M	Trajectory Prediction and Management
TS	Technical Specification
UAC	Upper Airspace Control
UIR	Upper Flight Information Region
V&V	Validation and Verification
VFR	Visual Flight Rules

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Term	Definition
VSP	Variable System Parameter
XFL	Exit Flight Level
WP	Work Package



2 General Functional block Description

2.1 Context

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- The following figure gives an overview of the role of the Monitoring Aids Functional Block.
- 350 The information about each functional sub-block is detailed in section 2.6.1.
- The Functional Blocks other than those in interface with MONA Functional Block are shown here for information.

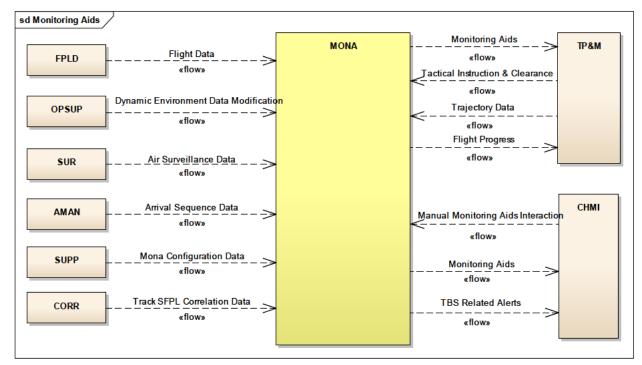


Figure 3: Monitoring Aids (MONA) Functional Block

As specified in 10.1.7 deliverable D120 "Technical Architecture Description - Cycle 2015 [6], the Monitoring Aids functional block encompasses the following functions:

- Flight Trajectory deviation and conformance monitoring: detects if a controlled aircraft deviates from its planned trajectory, notifying deviation warnings to the concerned sectors.
- Tactical Instruction and Clearance conformance monitoring: detects if a controlled aircraft deviates from the issued clearance/instruction and notifies the current executive controller.
- Flight progress monitoring and update: this function keeps the trajectory updated along the progress of the flight. It also detects certain events such as take-off, missed approach and landing.
- Reminder tools: reminder of instructions to be issued.
- Direct and Free Routing monitoring: detects if a controlled aircraft deviates from its planned trajectory in a Free Route Environment (DRA/FRA), where it is hard to spot if a turn is due to a user preferred planned route or to an unexpected manoeuver.



2.2 Functional block Modes and States

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2.3 Major Functional block Capabilities

- The requirements have been grouped according the following breakdown structure. 375
- 376 Functional requirements:
- 377 Eligibility,
- 378 Lateral conformance,
- 379 Vertical Rate conformance,
- CFL conformance, 380
- Level Bust, 381
- 382 NoTT monitoring,
- Potential Coordination Failure, 383
- Mode-S DAP conformance, 384
- 385 SID and STAR constraints conformance,
- Conformance monitoring requirements related to Aircraft Derived Data 386
- Interface requirements: 387
- Surveillance 388
- Output 389
- 390 Input

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391 HMI requirements

2.4 User Characteristics

ANSP / ATS Unit ACC, APP (Civ., Mil.)	Air Traffic Controller • Executive Controller • Planning Controller	Х
ANSP / ATS Unit ACC, APP (Civ., Mil.)	ATS Supervisor	Х

Table 3: User Characteristics

395 **User Characteristics**

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Technical staff in charge of maintenance, supervision, offline parameterization, should be able to monitor the Conformance Monitoring system by a basic graphical interface or a command line interface.

User Expectations

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From the air traffic controllers' point of view some important expectations towards the monitoring system are assumed to be the following (to be refined after input from ops projects and validation feedback)

- The main purpose is to relieve monitoring workload and free mental resources of the controller for other tasks or more traffic.
- In order to relieve the monitoring load of the controller and make him rely on the system:
 - The system has to be reliable (if it is not reliable, controller has to keep monitoring himself)
 - It has to be clear whether the system is correctly monitoring a flight or not (if it is unclear whether the system is doing the job, controller himself has to keep monitoring)
 - It has to be clear with regard to which profile the system is monitoring (if it is not clear with regard to which profile the system is monitoring the controller cannot make good use of surrounding airspace)
 - The system logic should be transparent. It should be clear why a warning is presented or not. (if a warning is presented, controllers have to take corrective actions and potentially instruct/explain to pilots, they can only do so when they understand what went wrong)
 - The system should represent an understanding of "conformance/non-conformance" which is shared to a reasonable extent by the controller.
 - The system should minimize false/nuisance warnings. (However, due to the safety criticality of the system, when the controller relies on the system to do some monitoring, it may be better to have some false warnings than missed ones).

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2.5 Operational Scenarios

Operational scenarios that illustrate the use of the Conformance Monitoring functionality are included 435 in Chapter 5 of the P04.07.02-D28, OSED 4 [8] and 04.07.02-D37 Free Route OSED [9]. The general 436 description of how Conformance Monitoring will be performed in TMA is included in the new SESAR 437 438 operating Method (Chapter 3.2 of the P05.07.02-D77 Preliminary V2 OSED for Step 1 [11]), also the 439 use cases for different density and complexity environments are depicted in Chapter 5 of the same 440 document.

2.6 Functional

2.6.1 Functional decomposition

- The functional view of how the MONA functional block participates in realising the operational needs 443 has already been introduced in section 2.1. 444
- 445 As detailed in the Figure 3, the Precision Conformance Monitoring System has interfaces with the following key external systems and actors: 446
- 447 Surveillance Data Processing and Distribution System (SUR) - This part of ATM systems provides an airspace situational awareness to user (air traffic controllers, ATM systems...). 448
 - Trajectory Management and Flight Data Processing / Trajectory Management (TP&M) This part of ATM systems provides flight plan (planned route) for each controlled aircraft (via CFMU, operator...) to user (ATM systems).
 - Air Traffic Controllers (CHMI) Some information are displayed at controller work positions via HMI (warning of non-conformance, kind of deviations...). The operator can then amend its control situation (new clearance, route...) through the HMI system.
- A detailed overview of the other interfaces is available on Technical Specification ATC System 455 Baseline documentations delivered by P10.01.07 [6] 456

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461 462 The Figure 4 shows instead the functional decomposition for Conformance Monitoring according to Major Functional block Capabilities

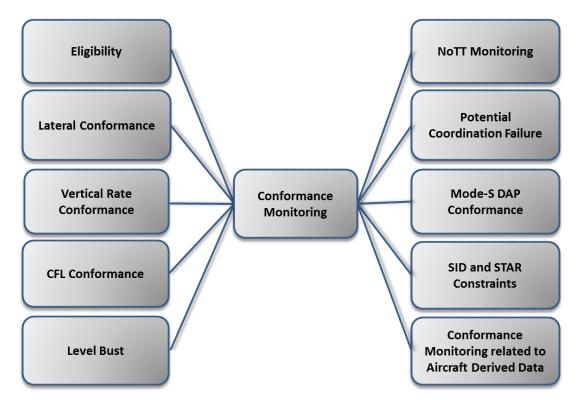


Figure 4: Conformance Monitoring Functional Breakdown

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- **Eligibility** this function is responsible for determining the eligibility of flights for Conformance Monitoring. The function may also offer the ability to exclude specific flights from monitoring.
- Lateral Conformance Monitoring this function provides warnings when a monitored flight does not conform with lateral clearances and instructions (e.g. route and headings) The warnings are removed when the lateral deviation is no longer present.
- Vertical Rate Conformance Monitoring this function provides a warning actual rate differs from the cleared vertical rate by more than a parameter. The warnings are removed when the vertical rate deviation is no longer present.
- 474 **CFL Conformance Monitoring** this function provides a warning when the aircraft does not move towards the CFL, or when the AFL of a levelled aircraft differs from the CFL by more than a threshold. The warnings are removed when the CFL deviation is no longer present.
- Level Bust Monitoring this function provides a warning when the actual vertical rate exceeds a rate threshold so that the aircraft is predicted to exceed the CFL. The warnings are removed when the Level Bust deviation is no longer present.
- NoTT Monitoring this function provides a warning when there is no tactical or deviation trajectory provided for a flight (and consequently there are not valid flight data available to be monitored).
- Potential Coordination Failure Monitoring this function provides a coordination failure warning when difference between the planned entry/exit condition and the coordinated entry/exit condition differs by more than a VSP threshold.



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- Edition: 00.04.00
- 485 Mode-S DAP Conformance Monitoring - this function provides warning when Mode-S selected altitude differs from CFL. The warning is removed as soon as the Mode-S selected altitude becomes 486
- 487 equal to CFL.
- SID and STAR Constraints Conformance Monitoring this function provides warning when flying 488
- on a SID or on a STAR at a waypoint configurable vertical constraints are violated. 489
- Conformance Monitoring related to Aircraft Derived Data this function provides warning when 490
- CTA vs RTA deviation or ATA vs ETA deviation are detected and when there is a mismatch with the 491
- 492 aircraft derived information (e.g. actual IAS provided by aircraft via ADS).
- 2.6.2 Functional analysis 493
- 494 See 2.6.1
- 2.7 Service View 495
- 496 N/A

3 Functional block Functional and non-Functional Requirements

499 3.1 Capabilities

The following structure was shown in section 2.3. This chapter itemises the requirements associated with each system capability in the list below.

- 502 Functional requirements:
- 503Eligibility

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- Lateral conformance
- Vertical Rate conformance
- CFL conformance
- 507 Level Bust
- NoTT conformance
- Potential Coordination Failure
- Mode-S DAP conformance
- SID and STAR constraints conformance
- Conformance monitoring requirements related to Aircraft Derived Data
- 513 Interface requirements:
- Surveillance
- 515
 Output
- 516 Input
- HMI requirements

518 3.1.1 Functional Requirements

This section presents the functional requirements defined for Phase 2 and Phase 3.

3.1.1.1 Eligibility Requirements

3.1.1.1.1 Flights Trajectory Eligibility

523 [REQ]

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[112]	
Identifier	REQ-10.04.02-TS-0001.0010
Requirement	All correlated flights with a planned or a tactical trajectory shall be eligible for Conformance Monitoring.

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Title	Eligibility for conformance monitoring
Status	<validated></validated>
Rationale	Flight plan correlated with an ADS-C track, will be eligible too. Planned trajectories modified upon controller clearances will be eligible too. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

524 525 526

[REQ Trace]

Linked Element Type	Identifier	Compliance
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<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0001	<full></full>
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3.1.1.1.2 Conformance Monitoring Processing

529 [REQ]

Identifier	REQ-10.04.02-TS-0001.0022		
Requirement	For a flight eligible for conformance monitoring, the conformance monitoring function shall compare track state vector of an aircraft with FP clearance data when track data or FP clearance data are updated.		
Title	Continuous monitoring of track data and clearance data		
	Continuous monitoring of track data and clearance data <validated></validated>		
Status	< validated >		
Rationale	Track state vector is track data provided periodically by the surveillance. In the event that the track data is not received for a time parameter (associated to the track distribution period), the flight is considered as not-correlated (due to track lost) so it is not subject to conformance monitoring. The FP clearance data is provided as a trajectory or as an horizontal and a vertical clearance. Both data defines two 4D positions to be compared to obtain a conformance status. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.		
Category	<functional></functional>		
Validation Method	<live trial=""></live>		
	<real simulation="" time=""></real>		
Verification Method	<test></test>		

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531 [REQ Trace]

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533 [REQ]

[11=04]				
Identifier	REQ-10.04.02-TS-0001.0026			
Requirement	When flight is following a SID at or below 120 meters above DER (runway),			
-	the conformance monitoring shall not detect any warning.			
Title	Conformance Monitoring at or below 120 meters above DER			
Status	<in progress=""></in>			
Rationale	The inhibition of Conformance Monitoring in the area at or below 120 meters above DER (Departure End of the Runway) will be performed through geographical filters off line configured. Implementation not requested in any validation exercise supported by P10.04.02			
Category	<functional></functional>			
Validation Method	<live trial=""></live>			
	<real simulation="" time=""></real>			
Verification Method	<test></test>			

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[ITE G ITGGG]			
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<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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[REQ]

[KEQ]			
Identifier	REQ-10.04.02-TS-0001.0027		
Requirement	When a flight is flying a SID between 120 m height above DER and MSA or simply above MSA, the conformance monitoring shall detect warning according to a dedicated vertical tolerance.		
Title	Conformance Monitoring warnings according to a dedicated vertical tolerance		
Status	<in progress=""></in>		
Rationale	 In case of flight above DER and MSA: Waypoint with a vertical constraint of "at ", the vertical tolerance for providing a warning shall be ± 100 ft; Waypoint with a vertical constraint of "at or above", the vertical tolerance for providing a warning shall be - 100 ft; Waypoint with a vertical constraint of "at or below", the vertical tolerance for providing a warning shall be + 100 ft. In case of flight above MSA: 		

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<Test>

	 Waypoint with a vertical constraint of "at ", the vertical tolerance for providing a warning shall be ± 150 ft; Waypoint with a vertical constraint of "at or above", the vertical tolerance for providing a warning shall be - 150 ft; Waypoint with a vertical constraint of "at or below", the vertical tolerance for providing a warning shall be + 150 ft. Implementation not requested in any validation exercise supported by P10.04.02 	
Category	<functional></functional>	
Validation Method	<live trial=""></live>	
	<real simulation="" time=""></real>	

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Verification Method

[aa]			
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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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3.1.1.2 Lateral Conformance Requirements

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[REQ]

Identifier	REQ-10.04.02-TS-0001.0023
Requirement	Upon a NoTT deviation detection, the Conformance Monitoring shall discard
	any Route Deviation detection until NoTT deviation is removed.
Title	Conformance monitoring discarding due to NoTT deviation detection
Status	<validated></validated>
Rationale	Route Deviation is discarded since no route information are available to check conformance. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

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[REQ Trace]

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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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550 [REQ]

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Identifier	REQ-10.04.02-TS-0001.0030
Requirement	When the track is outside of the flight path and the track is also outside the radius around a waypoint of the flight route, the Conformance Monitoring function shall detect a route deviation.
Title	Route Deviation Detection for a flight plan.
Status	<validated></validated>
Rationale	Track will be identified as outside of the flight path, if the distance between the horizontal position of the track and its perpendicular projection on the planned trajectory or tactical trajectory is bigger than a distance parameter. Thresholds for distance between the horizontal position of the track and its perpendicular projection on the (planned or tactical) trajectory and threshold for radius around the waypoint can be defined as different parameters. This requirements specifies the case when no heading clearance is on going; in case there is a heading clearance applied to a flight, the conformance monitoring detects a route deviation if the flight heading does not comply the cleared one. Conformance Monitoring will check route deviation at a rate of at least once per a VSP configurable time. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

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[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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[REQ]

Identifier	REQ-10.04.02-TS-0001.0050
Requirement	Upon controller entry, to a flight in lateral deviation, of a new assigned route,
	heading with which the system track is in conformance, the conformance
	monitoring shall remove the lateral deviation warning.
Title	Removal of lateral deviation warning after new route assigned from the
	controller
Status	<validated></validated>
Rationale	Note: baseline requirement, included because explicitly necessary for prototype
	functionality
	The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-
	VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""></live>

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	<real simulation="" time=""></real>
Verification	<test></test>
Method	

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[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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[REQ]

Identifier	REQ-10.04.02-TS-0001.0051
Requirement	For a flight with a Route Deviation, the Conformance Monitoring shall remove
	the route deviation if the track is inside the flight path.
Title	Route Deviation Removal.
Status	<validated></validated>
Rationale	In this case Route Deviation is removed due to the track returning inside the flight path (without any new clearance coming from the controller) The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

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[REQ Trace]

[🔾]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER_ATC_157	<full></full>
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[IVEQ]	
Identifier	REQ-10.04.02-TS-0001.0450
Requirement	The Conformance Monitoring shall accept dedicated lateral threshold values to
	apply for flights approved for particular PBN application.
Title	Lateral tolerance considering PBN
Status	<in progress=""></in>
Rationale	PBN applications are referred to instrument flight procedures (SID, STAR, IAP). It will be possible to implement a set of procedures (i.e STARs) within a TMA which not all of them require same PBN specification (e.g.one STAR may

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	requires RNAV1 and another RNP2), The conformance monitoring should accept different accuracy threshold depending on the accuracy of the required specification. Obviously within the TMA can fly PBN and Non PBN aircraft approved. Implementation not requested in any validation exercise supported by P10.04.02
Category	<functional></functional>
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Verification Method	<test></test>

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[REQ Trace]

[~			
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3.1.1.3 Vertical Rate Conformance Requirements

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[REQ]

[1,124]	
Identifier	REQ-10.04.02-TS-0001.0141
Requirement	For a flight in vertical manoeuvre to a not reached CFL, the Conformance Monitoring function shall detect a vertical rate deviation if the following conditions are fulfilled: a) No CFL deviation or level bust is detected, and b) vertical latency time after a new vertical clearance has been elapsed, and c) the new CFL is not reached, and d) actual vertical rate is lower than the minimum vertical rate into the direction
	to CFL, or actual rate differs from the cleared vertical rate by more than a parameter.
Title	Vertical Rate Deviation Detection
Status	<validated></validated>
Rationale	A CFL is reached when the difference between AFL and CFL is lower than a threshold.
	The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

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[REQ Trace]

[NEQ Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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576 [REQ]

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Identifier	REQ-10.04.02-TS-0001.0142
Requirement	For a flight with a Vertical Rate Deviation, the Conformance Monitoring shall discard the Vertical Rate Deviation, if any of the following conditions is fulfilled: a) CFL is reached (difference between AFL and CFL is lower than a threshold) b) actual vertical rate is higher than the minimum vertical rate into the direction of the CFL, and actual rate differs from the cleared vertical rate less than a parameter
Title	Vertical Rate Deviation removal due to flight.
Status	<validated></validated>
Rationale	As a summary, a Vertical Deviation is removed when it is no longer detected, so the detection conditions are no longer fulfilled. Consequently, conditions to discard a Vertical Rate Deviation are the negative case of the Vertical Rate Deviation Detection conditions. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

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[REQ Trace]

[112 0 11000]			
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<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A
<allocated_to></allocated_to>	<project></project>	10.04.02	N/A

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3.1.1.4 CFL Conformance Requirements

581 582 [REQ]

Identifier	REQ-10.04.02-TS-0001.0151	
Requirement	For a CFL previously reached, the Conformance Monitoring shall detect a CFL	
	deviation if the AFL differs from the CFL by more of a threshold.	
Title	CFL Deviation Detection for CFL Reached	
Status	<validated></validated>	
Rationale	A CFL is reached from the moment when the difference between AFL and CFL	
	is lower than a threshold.	
	The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-	
	VP-741 and EXE-04.03-VP-798.	
Category	<functional></functional>	
Validation Method	<live trial=""></live>	
	<real simulation="" time=""></real>	
Verification Method	<test></test>	

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[REQ Trace]

[INE G Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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[REQ]

[INEQ]	
Identifier	REQ-10.04.02-TS-0001.0152
Requirement	For a CFL not reached, the Conformance Monitoring shall detect a CFL
	deviation if current AFL is outside a band level between the previous AFL and
	the CFL.
Title	CFL Deviation Detection for CFL Not Reached
Status	<validated></validated>
Rationale	A CFL is not reached from the moment that it is input to the moment when the
	difference between AFL and CFL is lower than a threshold.
	The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-
	VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

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[REQ Trace]

[INE & FIACC]			
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591 592 593

[REQ]

L3		
Identifier	REQ-10.04.02-TS-0001.0153	
Requirement	For a flight with a CFL Deviation, if the AFL differs from the CFL by less than a	
	threshold, the Conformance Monitoring shall discard the CFL Deviation.	
Title	CFL Deviation removal due to flight return to cleared level.	
Status	<validated></validated>	
Rationale	The CFL Deviation may be removed due to a new CFL (CFL is updated) or due to the flight returning to current CFL (AFL is updated). Both cases are included in this requirement. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-	
	VP-741 and EXE-04.03-VP-798.	
Category	<functional></functional>	
Validation Method	<live trial=""></live>	
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Verification Method	<test></test>	

594 595

[REQ Trace]

Relationship Linked Element Type Identifier Compliance	_				
		Relationship	Linked Element Type	Identifier	Compliance

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3.1.1.5 Level Bust Requirements

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[REQ]

ַ[אבע]	
Identifier	REQ-10.04.02-TS-0001.0181
Requirement	For a flight in vertical manoeuvre close to the CFL, the Conformance
	Monitoring shall detect a Level Bust deviation if the actual vertical rate exceeds a rate threshold and no CFL Deviation is detected.
Title	Level Bust Deviation Detection
Status	<validated></validated>
Rationale	A flight is considered in a vertical manoeuvre close to the CFL, when the difference between AFL and CFL is lower than an additional threshold. This threshold is independent of the reached CFL defined in other requirements. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

600 601

[REQ Trace]

[NEW HOOC]		1	
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[REQ]

[1/12/4]		
Identifier	REQ-10.04.02-TS-0001.0182	
Requirement	For a flight with a Level Bust Deviation, if actual vertical rate is less than an	
	threshold, the Conformance Monitoring shall discard the Level Bust Deviation.	
Title	Level Bust Deviation removal due to vertical rate correction.	
Status	<validated></validated>	
Rationale	As a summary, a Level Bust Deviation is removed when it is no longer detected, so the detection conditions are no longer fulfilled. Consequently, conditions to discard a Level Bust Deviation are the negative case of the Level Bust Deviation Detection conditions. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.	
Category	<functional></functional>	

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Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

606 607

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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3.1.1.6 NoTT Conformance Requirements

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[REQ]

[IVEQ]	
Identifier	REQ-10.04.02-TS-0001.0191
Requirement	The Conformance Monitoring shall detect a NoTT Deviation if
	a) no valid route information is available for a flight;
	or
	b) the aircraft is beyond or before its cleared (filed) route.
Title	NoTT Deviation Detection
Status	<validated></validated>
Rationale	In case of NoTT deviation, tactical trajectory cannot be calculated because of
	missing input data.
	A flight does not have valid flight data for monitoring when no tactical or
	deviation trajectory is available. If any of them is calculated, the NoTT deviation
	is not detected.
	The requirement has been validated in EXE-04.07.02-VP-501.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

612 613

[REQ Trace]

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614 615 616

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[REQ]

Identifier	REQ-10.04.02-TS-0001.0194
Requirement	For a flight with a NoTT deviation detected, the Conformance Monitoring shall discard the NoTT Deviation previously detected, if the flight has a Tactical Trajectory or a Deviation Trajectory, and the flight is inside the cleared (filed) route.
Title	NoTT Deviation removal

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Status	<in progress=""></in>
Rationale	The conditions for NoTT Deviation removal are the opposite (in a logical sense) of the conditions NoTT Deviation detection. Implementation not requested in any validation exercise supported by P10.04.02
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

618 619

[REQ Trace]

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3.1.1.7 Potential Coordination Failure Requirements

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[REQ]

ַ[גבע]	
Identifier	REQ-10.04.02-TS-0001.0170
Requirement	The conformance monitoring shall detect an entry/exit coordination failure when the difference between the planned entry/exit condition and the coordinated entry/exit condition differs by more than a VSP time or level threshold.
Title	Coordination conditions failure warning
Status	<validated></validated>
Rationale	Entry/exit condition (e.g. COP XFL) The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

624 625

[REQ Trace]

[INEQ Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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[REQ]

['\-\&]	
Identifier	REQ-10.04.02-TS-0001.0175
Requirement	When an entry and/or exit coordination failure is detected, the conformance monitoring shall issue the warning to the exit sector CWP and/or entry sector CWP.
Title	Entry/Exit coordination failure

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Status	<validated></validated>
Rationale	The entry/exit coordination failure warning will have to be distributed and displayed to the CWP associated to the interested entry/exit sectors. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

630 631

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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3.1.1.8 Mode-S DAP Conformance Requirements

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[REQ]

L3	
Identifier	REQ-10.04.02-TS-0001.0161
Requirement	Upon a latency time after a new vertical clearance has been elapsed, if the
	Mode S Selected Altitude differs to CFL, the Conformance Monitoring function
	shall detect a Mode S Altitude Deviation.
Title	Mode S Selected Altitude Deviation Detection with clearance latency.
Status	<validated></validated>
Rationale	In order to avoid that Mode S Selected Altitude Deviation is raised every time a
	new CFL is input, a time latency condition is added.
	The requirement has been validated in EXE-04.07.02-VP-501 and EXE-
	04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

637 638

[REQ Trace]

[INE & ITAOO]			
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
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639 640

[REQ]

[NEQ]	
Identifier	REQ-10.04.02-TS-0001.0163
Requirement	For a flight with a Mode S Altitude Deviation, if the Mode S Selected Altitude is equal to CFL, the Conformance Monitoring shall remove the Mode S Altitude Deviation.
Title	Mode S Selected Altitude Deviation removal
Status	<validated></validated>
Rationale	Deviation removal condition may be achieved due to a CFL updated or due to

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	a Mode S Selected Altitude, both cases will achieve the deviation removal. The requirement has been validated in EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

641 642

[REQ Trace]

[🔾]			
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643 644 645

[REQ]

[KEQ]	
Identifier	REQ-10.04.02-TS-0001.0165
Requirement	Upon a latency time after a Mode S Selected Altitude update has been
	elapsed, if the Mode S Selected Altitude differs to CFL, the Conformance
	Monitoring function shall detect a Mode S Altitude Deviation.
Title	Mode S Selected Altitude Deviation Detection with pilot latency.
Status	<validated></validated>
Rationale	In order to avoid nuisance Mode S Selected Altitude Deviation if the pilot enters the new clearance faster than the controller, a time latency condition is added. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

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[INE & FIGOU]			
Relationship	Linked Element Type	Identifier	Compliance
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3.1.1.9 SID and STAR constraints conformance requirements

[RFQ]

[KEQ]	
Identifier	REQ-10.04.02-TS-0001.0024
Requirement	For a flight cleared to IAF, the Conformance Monitoring shall detect a vertical deviation, if the AFL is lower than the vertical constraint associated to the IAF more than an adapted parameter.
Title	Vertical deviation when AFL is lower than the vertical constraint
Status	<in progress=""></in>
Rationale	A flight cleared direct to IAF should not descend below the level defined for the IAF. Implementation not requested in any validation exercise supported by P10.04.02

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Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

651 652

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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653 654

[REQ]

[REQ]	
Identifier	REQ-10.04.02-TS-0001.0400
Requirement	For a "at or above" vertical constraint associated to an STAR waypoint, the Conformance Monitoring shall detect a STAR constraint deviation, if the track is inside the radius around the STAR waypoint, the STAR waypoint is not overflown and the AFL is lower than the vertical constraint in more than an adapted parameter.
Title	STAR constraint at or above
Status	<in progress=""></in>
Rationale	This monitoring is to detect if the flight is not going to fulfil the vertical constraint. Implementation not requested in any validation exercise supported by P10.04.02
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

655 656

[REQ Trace]

[REG Hadd]			
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<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

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3.1.1.10 Conformance monitoring requirements related to Aircraft Derived Data

660 [REQ

[REQ]	
Identifier	REQ-10.04.02-TS-0001.0180
Requirement	All detected deviations shall be available to be displayed as non-conformance warnings in the respective position sector.
Title	Displaying availability of non-conformance warnings.
Status	<validated></validated>
Rationale	All detected deviations has to be available to be displayed, that does not mean than all detected deviation has to be displayed (may be configured, adapted, or manually inhibited). The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""></live>

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Project ID 10.04.02

D44 - Consolidated Conformance Monitoring System Requirements

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Verification	<test></test>
Method	

661

662 [REQ Trace]

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663 664

[REQ]

[112]	
Identifier	REQ-10.04.02-TS-0001.0190
Requirement	The type of the detected deviation shall be available for presentation for a displayed non-conformance warning to the respective position sector.
Title	Availability of type of trajectory deviation for non-conformance warning.
Status	<validated></validated>
Rationale	The precise non-conformance warnings to be defined and which deviations generate each warning display are implementation. The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
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665 666

[REQ Trace]

[INE G. HAGO]			
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667

668 [REQ]

[\circ	
Identifier	REQ-10.04.02-TS-0001.0230
Requirement	Whenever conformance monitoring warning is provided, it shall be made
	available for presentation to the respective position sector, until it is removed by
	the Conformance Monitoring function.
Title	Presentation and removal of conformance warning
Status	<validated></validated>
Rationale	The non-conformance warning to be distributed, displayed and removed to the
	interested position sector
	The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-
	VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""></live>
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Verification	<test></test>
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669

670 [REQ Trace]

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671 672

[REQ]

[REQ]	
Identifier	REQ-10.04.02-TS-0003.0240
Requirement	When a CTA vs RTA deviation is detected, the conformance monitoring shall provide a lighting warning to the CWP
Title	Presentation of CTA vs RTA deviation
Status	<in progress=""></in>
Rationale	The non-conformance warning to be distributed, displayed and removed to the interested position sector. Implementation not requested in any validation exercise supported by P10.04.02
Category	<pre><functional></functional></pre>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

673 674

[REQ Trace]

[[1] 4 [1]			
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676 [REQ]

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Identifier	REQ-10.04.02-TS-0001.0410		
Requirement	When CTA and RTA information are available, the conformance monitoring		
	shall generate a warning when, over a configurable waypoint, aircraft CTA		
	differs from RTA more than a configurable time parameter, at each correlation		
	period cycle.		
Title	CTA vs RTA deviation		
Status	<in progress=""></in>		
Rationale	The conformance monitoring should consider also the information which come		
	from the aircraft which should be used for improving Conformance functionality,		
	The tolerance to raise this warning is constrained by the correlation period, but		
	the correlation period can be synchronized on sensor (generally 4 seconds in		
	approach), periodic (each x seconds) or aperiodic(each update of track).		
	Implementation not requested in any validation exercise supported by		
	P10.04.02		
Category	<functional></functional>		
Validation Method	<live trial=""></live>		
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Verification Method	<test></test>		

677 678

[REQ Trace]

[REQ Trace]			
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680 [REQ]

Identifier	REQ-10.04.02-TS-0001.0430
Requirement	When Aircraft Derived Data are available, the conformance monitoring should detect a IAS deviation warning if the actual IAS (provided by the aircraft) differs from cleared IAS.
Title	Actual IAS vs Cleared IAS deviation
Status	<in progress=""></in>
Rationale	Actual IAS will be provided by aircraft via ADS. Implementation not requested in any validation exercise supported by P10.04.02
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

681 682

[REQ Trace]

[\ \ \ \ \ \ \			
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684 [REQ]

[, , = x,]		
Identifier REQ-10.04.02-TS-0001.0460		
Requirement When Aircraft Derived Data or EPP data are available, the conformance		
	monitoring shall compare the future positions to the reference trajectory and in	

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	case of deviation issue a warning indicating " in "XXX" minutes, "Flight ID" shall be deviated from the latest clearance.
Title	Aircraft Derived Data or EPP usage
Status	<in progress=""></in>
Rationale	It is expected that conformance monitoring tool not just comparing present position against reference trajectory, but also future positions. Implementation not requested in any validation exercise supported by P10.04.02
Category	<functional></functional>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

685 686

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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3.2 Adaptability

No adaptability system requirements can be derived at this time. This section can be revised when more information becomes available.

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3.3 Performance Characteristics

692 [REO]

ַ[אבע]	
Identifier	REQ-10.04.02-TS-0001.0470
Requirement	The conformance monitoring shall be able to manage at least 200 flights per control area (TMA or ACC).
Title	Conformance monitoring capacity
Status	<validated></validated>
Rationale	The number of managed flights per control area includes flights under control (in live status) or within the look ahead time per each control area. Capacity for future flights (not within the look ahead time) or additional control areas are outside this number. The requirement has been validated in EXE-04.07.02-VP-741.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

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[INEQ Hace]			
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3.4 Safety & Security

The requirements included in this section have been derived from the latest available P04.07.02 D30 Preliminary Safety and Performance Requirements for MTCD/TCT_4. This section will be revised when some more information becomes available.

700 [REQ]

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[:]			
Identifier	REQ-10.04.02-TS-0002.0100		
Requirement	The probability of Loss of TC-Aid shall be no more than 3.33E-07 per flight		
	hour.		
Title	Acceptability of Loss of TC-Aid		
Status	<in progress=""></in>		
Rationale	Safety requirement is defined in relation to the safety objectives derived from the Failure Case Analysis workshop (P04.07.02 Task 93). Implementation not requested in any validation exercise supported by P10.04.02		
Category	<safety></safety>		
Validation Method	<live trial=""></live>		
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Verification Method	<analysis></analysis>		

701 702

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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703

704 [REQ]

[1124]		
Identifier	REQ-10.04.02-TS-0002.0200	
Requirement	The probability of Delay of the TC-Aid shall be no more than 3.33E-07 per flight	
	hour.	
Title	Acceptability of Delay of TC-Aid	
Status	<in progress=""></in>	
Rationale	Safety requirement is defined in relation to the safety objectives derived from the Failure Case Analysis workshop (P04.07.02 Task 93). Implementation not requested in any validation exercise supported by P10.04.02	
Category	<safety></safety>	
Validation Method	<live trial=""></live>	
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Verification Method	<analysis></analysis>	

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[REQ Trace]

[NEW Have]			
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708 [REQ]

	[1124]	
Identifier REQ-10.04.02-TS-0002		REQ-10.04.02-TS-0002.0300
	Requirement	The probability of Corruption (Undetected) of the TC-Aid shall be no more than 3.33E-07 per flight hour.

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Title	Acceptability of Corruption (Undetected) of TC-Aid	
Status	<in progress=""></in>	
Rationale	Safety requirement is defined in relation to the safety objectives derived from the Failure Case Analysis workshop (P04.07.02 Task 93). Implementation not requested in any validation exercise supported by P10.04.02	
Category	<safety></safety>	
Validation Method	<live trial=""> <real simulation="" time=""></real></live>	
Verification Method	<analysis></analysis>	

709 710

[REQ Trace]

[,]			
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712 [REQ]

[REQ]			
Identifier	REQ-10.04.02-TS-0002.0400		
Requirement	The probability of Corruption (Detected) of the TC-Aid shall be no more than		
	1.00E-05 per flight hour		
Title	Acceptability of Corruption (Detected) of TC-Aid		
Status	<in progress=""></in>		
Rationale	Safety requirement is defined in relation to the safety objectives derived from		
the Failure Case Analysis workshop (P04.07.02 Task 93).			
	Implementation not requested in any validation exercise supported by		
	P10.04.02		
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Verification Method	<analysis></analysis>		

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[INE & HACC]			
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715716

[REQ]

[NEQ]				
Identifier	REQ-10.04.02-TS-0002.0500			
Requirement	The frequency of occurrence of detected corruption of input data from			
Trajectory Deviation Detection function shall not be greater that				
	hr)			
Title	Frequency of detected corruption of input data			
Status	<in progress=""></in>			
Rationale	Safety requirement for 4D Trajectory-Based Operations for separation			
management using RNAV/PRNAV. Implementation not requested in any validation exercise supported by				
				P10.04.02
Category	<safety></safety>			
Validation Method	<live trial=""></live>			
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[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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[REQ]

Identifier	REQ-10.04.02-TS-0002.0600			
Requirement The frequency of occurrence of undetected corruption of input				
	Trajectory Deviation Detection function shall not be greater than 0.4x10-7(/flt			
	hr)			
Title	Frequency of undetected corruption of input data			
Status	<in progress=""></in>			
Rationale	Safety requirement for 4D Trajectory-Based Operations for separation			
	management using RNAV/PRNAV.			
	Implementation not requested in any validation exercise supported by			
P10.04.02				
Category	<safety></safety>			
Validation Method				
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Verification Method	<analysis></analysis>			

721 722

[REO Trace]

[INE Q TIACE]			
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3.5 Maintainability

Requirements related to Maintainability have not been derived from 04.07.02 OSED. This section will be revised when some more information will be available.

3.6 Reliability

Requirements related to Reliability have not been derived from 04.07.02 OSED. This section will be revised when some more information will be available.

3.7 Functional block Internal Data Requirements

731 These requirements are internal to the design of the prototypes and will be detailed when 04.07.02 performance requirements will be available. 732

3.8 Design and Construction Constraints

734 In line with the 10.1.7 ATC system specification, the following approach will be used.

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- The System shall be designed as a modular and open architecture based on defined and established industry standards.
- The software design shall adopt a hierarchy scheme in form of a set of application software layers that are at different abstraction levels.
- It shall be possible to integrate further additional components that may be defined in subsequent development steps.

3.9 Functional block Interface Requirements

- 742 This section contains the specification of requirements for interfaces among different functional blocks.
- In particular it contains system interface requirements distributed in Surveillance, Output and Input Interface requirements.
- This section includes also HMI requirements which introduces high level specifications related to interface among MONA and CHMI functional blocks.

3.9.1 System Interface Requirements

The sections below present the interface requirements identified for the Monitoring Aid functional block.

3.9.1.1 Surveillance Interface Requirements

752 [REQ]

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[INEQ]	
Identifier	REQ-10.04.02-TS-0001.0320
Requirement	The Conformance Monitoring shall process Track Information; received Track Information has to be QNH corrected in order to be compared with vertical clearances
Title	Processing of track information
Status	<validated></validated>
Rationale	The minimum surveillance information used for each received track by Conformance Monitoring are Track position (Latitude/longitude, Altitude) Track associated time: last update The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

754 [REQ Trace]

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	[🔾]			
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3.9.1.2 Output Interface Requirements

757 [REQ

[REQ]			
Identifier	REQ-10.04.02-TS-0001.0330		
Requirement	The Conformance Monitoring shall at least produce the following Deviation Detection data items in case of a non-conformance warning: • Type of non-conformance • Non-conformance measure • Time of non-conformance		
Title	Data items from a non-conformance warning		
Status	<validated></validated>		
Rationale	Type of non-conformance (e.g. lateral conformance, vertical rate conformance), Non-Conformance Measure (e.g. lateral left deviation, lateral right deviation), Time of non-conformance (when the non-conformance starts) The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.		
Category	<functional></functional>		
Validation Method	<live trial=""> <real simulation="" time=""></real></live>		
Verification Method	<test></test>		

758 759

[REQ Trace]

[
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER_ATC_157	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-04.07.02-SPR-CDR1.1190	<partial></partial>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-SPR-CDR2.1150	<partial></partial>
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<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0003	<partial></partial>
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A



<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A

760 761 [REQ]

_[REQ]			
Identifier	REQ-10.04.02-TS-0001.0340		
Requirement	Upon detection of a NoTT Deviation, a Route Deviation, a Speed Deviation, a CFL Deviation, a Vertical Deviation or a Level Bust Deviation for a flight, Conformance Monitoring shall report the deviation detected in order to trigger the deviation trajectory calculation for the flight.		
Title	Conditions for Deviation Trajectory calculation trigger		
Status	<validated></validated>		
Rationale	Any deviation will trigger the Deviation Trajectory instead the Tactical Trajectory calculation. This trigger will include whose deviations are detected in order to be applied in the deviation trajectory calculation. The requirement has been validated in EXE-04.03-VP-798.		
Category	<functional></functional>		
Validation Method	<live trial=""> <real simulation="" time=""></real></live>		
Verification Method	<test></test>		

762 763

[REQ Trace]

[NEQ Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<atms requirement=""></atms>	REQ-04.07.02-SPR-CDR1.1120	<partial></partial>
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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

764 765

[REQ]

[REQ]			
Identifier	REQ-10.04.02-TS-0001.0341		
Requirement	If all deviations for a flight are removed, the Conformance Monitoring shall report the absence of deviations to the TP&M for triggering the tactical trajectory calculation for the flight.		
Title	Tactical Trajectory Calculation Trigger due to absence of deviation		
Status	<validated></validated>		
Rationale	Conformance monitoring will report the absence of vertical and/or lateral deviation (both or any of them) to TP&M in order to calculate the tactical trajectory. The requirement has been validated in EXE-04.07.02-VP-501 and EXE-04.03-VP-798.		
Category	<functional></functional>		
Validation Method	<live trial=""></live>		
	<real simulation="" time=""></real>		
Verification	<test></test>		
Method			

766

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767 [REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
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<applies_to></applies_to>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

768

769

3.9.1.3 Input Interface Requirements

770

771 [REQ]

[NEQ]			
Identifier	REQ-10.04.02-TS-0001.0310		
Requirement	The Conformance Monitoring shall receive and use the planned trajectory (and every update of it) and controller clearances data for a flight as long as a system flight plan is available.		
Title	Processing of planned trajectory and controller clearances data		
Status	<validated></validated>		
Rationale	The trajectory information used by Conformance Monitoring is implementation detail. For example list of points with: Latitude/Longitude Level Time Velocity: horizontal, vertical Associated constraints, if any The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.		
Category	<functional></functional>		
Validation Method	<live trial=""> <real simulation="" time=""></real></live>		
Verification Method	<test></test>		

772 773

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
<satisfies></satisfies>	<enabler></enabler>	APP ATC 94	<full></full>
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<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0001	<partial></partial>
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<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0005	<full></full>
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<changed_because_of></changed_because_of>	<change order=""></change>	Change reference	N/A

774 775

[REQ]

[NEQ]	
Identifier	REQ-10.04.02-TS-0001.0350
Requirement	The Conformance Monitoring shall accept vertical and lateral threshold values.

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Title	Threshold inputs.
Status	<validated></validated>
Rationale	Vertical and lateral threshold represents threshold inputs taken into account to compute deviation The requirement has been validated in EXE-04.07.02-VP-501, EXE-04.07.02-VP-741 and EXE-04.03-VP-798.
Category	<functional></functional>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

776

777 [REQ Trace]

[INE & ITAGO]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
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<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A

778 779

[REQ]

[KEQ]	לבען		
Identifier	REQ-10.04.02-TS-0001.0360		
Requirement	The Conformance Monitoring shall accept acknowledgements from the HMI in response to deviation detections.		
Title	Acknowledgement inputs.		
Status	<in progress=""></in>		
Rationale	Acknowledgments from HMI will allow to give an indication that a kind of		
	response has been given to a detected deviation.		
	Implementation not requested in any validation exercise supported by P10.04.02		
Category	<functional></functional>		
Validation Method	<live trial=""></live>		
	<real simulation="" time=""></real>		
Verification	<test></test>		
Method			

780 781

[REQ Trace]

[INE & ITAOO]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<changed because="" of=""></changed>	<change order=""></change>	Change reference	N/A

782

783

3.9.2 HMI Requirements

This section shows general HMI requirements related with MONitoring Aids which have been identified.

786 [REQ]

[1/2/4]		
Identifier	REQ-10.04.02-TS-0002.0240	
Requirement	The CWP shall allow the controller to assign a new route or heading with	
	which the system track is in conformance in order to remove the deviation	

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Title	warning for a flight in lateral deviation Lateral deviation warning removal
Status	<validated></validated>
Rationale	Related to REQ-10.04.02-TS-0001.0050. If a flight in lateral deviation becomes in conformance with a new route assignment, the lateral deviation warning shall be removed by the conformance monitoring system (and, consequently, not displayed anymore). The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

787 788

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-04.07.02-SPR-CDR1.1210	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-SPR-CDR2.1140	<full></full>
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<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

789 790 791

[REQ]

Identifier	REQ-10.04.02-TS-0002.0250	
Requirement	The CWP shall display a warning to the exit and entry sector of a flight wh	
	a coordination failure is detected.	
Title	Display of an Entry/Exit coordination failure	
Status	<validated></validated>	
Rationale	Related to REQ-10.04.02-TS-0001.0175. The entry/exit coordination failure warning will have to be distributed and displayed to the CWP associated to the interested entry/exit sectors. The requirement has been validated in EXE-04.07.02-VP-741.	
Category	<hmi></hmi>	
Validation Method	<live trial=""></live>	
	<real simulation="" time=""></real>	
Verification Method	<test></test>	

792 793

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

794 795 796

[REQ]

_[. (= \infty]	
Identifier	REQ-10.04.02-TS-0002.0260
Requirement	The CWP shall allow the Controller to acknowledge in response to deviation detections.
Title	Controller acknowledge to deviations
Status	<in progress=""></in>

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Rationale	Acknowledgments from HMI will allow to give an indication that a kind of response has been given to a detected deviation. Related to REQ-10.04.02-TS-0001.0360. Implementation not requested in any validation exercise supported by P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

797 798

[REQ Trace]

Relationship	Linked Element Type	Identifier	Compliance
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799 800 801

[REQ]

ַ[תבע]		
Identifier	REQ-10.04.02-TS-0002.0270	
Requirement	The CWP shall display non-conformance warnings to the controller when	
	deviations are detected.	
Title	Display of the non-conformance warnings due to deviations	
Status	<validated></validated>	
Rationale	All detected deviations has to be available to be displayed, that does not necessarily mean that all detected deviations have to be displayed (they may be configured, adapted, or manually inhibited). Related to REQ-10.04.02-TS-0001.0180. The requirement has been validated in EXE-04.07.02-VP-741.	
Category	<hmi></hmi>	
Validation Method	<live trial=""></live>	
	<real simulation="" time=""></real>	
Verification Method	<test></test>	

802 803

[REQ Trace]

[INE GOO]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 91	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER_ATC_157	<full></full>
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804 805 806

[REQ]

[NEQ]	
Identifier	REQ-10.04.02-TS-0002.0280
Requirement	The CWP shall display the type of deviation detected for a non-conformance
	warning.
Title	Display of the type of deviation in a non-conformance warning
Status	<validated></validated>
Rationale	The precise non-conformance warnings to be defined and the related HMI customizations are implementation dependent. Related to REQ-10.04.02-TS-0001.0190.
	The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>

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Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

807 808

[REQ Trace]

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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

809 810 811

[REQ]

[INEQ]	
Identifier	REQ-10.04.02-TS-0002.0290
Requirement	The CWP shall display a conformance monitoring warning until it is removed
	by the Conformance Monitoring Function.
Title	Display and remove the monitoring warning.
Status	<validated></validated>
Rationale	The non-conformance warning to be distributed, displayed and removed to
	the interested position sectors. Related to REQ-10.04.02-TS-0001.0230.
	The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
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Verification Method	<test></test>

812 813

[REQ Trace]

[REQ Hace]			
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

814 815

816

[REQ]

[REQ]	
Identifier	REQ-10.04.02-TS-0002.0310
Requirement	The CWP shall display non-conformance warnings to the controller when
	deviations are detected by the TC-Aid.
Title	Display of a warning if the TC-Aid detects deviations
Status	<in progress=""></in>
Rationale	Warnings regarding deviations detected by the TC-Aid help to increase
	Controller awareness.
	Implementation not requested in any validation exercise supported by
	P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

817 818

[REQ Trace]

[INEQ Hace]			
Relationship	Linked Element Type	Identifier	Compliance

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<applies_to></applies_to>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

819 820 821

[REQ]

[KEQ]	
Identifier	REQ-10.04.02-TS-0002.0320
Requirement	The CWP shall remove the display of the warning to the controller if a
	deviation detected by the TC-Aid no longer exists
Title	Removal of the warning in case of a deviation no longer exists
Status	<in progress=""></in>
Rationale	In order not to disturb the Controller with already not-existing deviations, warnings notifying them should be removed from the CWP. Implementation not requested in any validation exercise supported by P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

822 823

[REQ Trace]

[112 0 11000]			
Relationship	Linked Element Type	Identifier	Compliance
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-04.07.02-SPR-CDR1.1210	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-SPR-CDR2.1030	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0002	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER ATC 91	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
<allocated_to></allocated_to>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
<applies_to></applies_to>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

824 825 826

[REQ]

[NEW]	
Identifier	REQ-10.04.02-TS-0002.0350
Requirement	The CWP shall display the following deviations between actual track data
	and controller clearance data:
	a) Route deviation (ROUTE);
	b) Vertical rate deviation (RATE);
	c) Cleared flight level deviation (CFL);
	d) No valid Flight Plan data
Title	Display deviations between actual track and controller clearance.
Status	<validated></validated>
Rationale	The controller should be aware of the deviations above described detected
	between the radar track and its clearances.
	The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

827 828

[REQ Trace]

[INE GOOD]			
Relationship	Linked Element Type	Identifier	Compliance
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-SPR-CDR2.1150	<partial></partial>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-INTEROP-0030.0003	<partial></partial>

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<satisfies></satisfies>	<enabler></enabler>	ER ATC 91	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
<allocated_to></allocated_to>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
<applies_to></applies_to>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

829 830 831

[REQ]

[KEQ]	
Identifier	REQ-10.04.02-TS-0002.0360
Requirement	The CWP shall display deviation warnings for aircraft depending on sector
-	frequency status and actual position.
Title	Display of deviation warnings based on frequency and actual position
Status	<in progress=""></in>
Rationale	Controller has to be informed with warnings about the deviations that occur if the flight is under control of the ATSU and the position of the flight to avoid overlapping with other sectors CWPs. Implementation not requested in any validation exercise supported by P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

832 833

[REQ Trace]

[&			
Relationship	Linked Element Type	Identifier	Compliance
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-04.07.02-OSED-0001.3019	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-SPR-CDR2.1040	<full></full>
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<satisfies></satisfies>	<enabler></enabler>	ER_ATC_91	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated_to></allocated_to>	<project></project>	10.04.02	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

834 835 836

[REQ]

[KEQ]	
Identifier	REQ-10.04.02-TS-0002.0370
Requirement	The CWP shall display a warning to the controller when any deviation from
	coordination conditions detected by the PC-Aid
Title	Display of a warning when PC-Aid detects deviations from coordination.
Status	<validated></validated>
Rationale	Controller should be alerted when deviations found by the PC-Aid in the
	coordination conditions,
	The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

837 838

[REQ Trace]

[REG HOOO]		11	
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER ATC 91	<full></full>
<satisfies></satisfies>	<enabler></enabler>	ER ATC 157	<full></full>
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<allocated_to></allocated_to>	<project></project>	10.04.02	N/A
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<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

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840 841

[REQ]

Identifier	REQ-10.04.02-TS-0002.0380
Requirement	The CWP shall display a warning after reception of Mode S DAP if a
	deviation is detected between controller clearance and Mode S DAP.
Title	Display of a warning if deviations between clearance and received Mode S
	DAP
Status	<validated></validated>
Rationale	Controller should be aware of the incongruence between different sources
	of information, including the clearances and the Mode S DAP.
	The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

842 843

[REQ Trace]

[INE G TIACC]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER_ATC_157	<full></full>
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<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated_to></allocated_to>	<project></project>	10.04.02	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

844 845 846

[RFQ]

ַ[KEQ]	
Identifier	REQ-10.04.02-TS-0002.0390
Requirement	The CWP shall display warning after a new controller clearance if a
	deviation is detected between controller clearance and Mode S DAP.
Title	Display of a warning if deviations between new clearance and Mode S DAP
Status	<validated></validated>
Rationale	Controller should be aware of the incongruence between different sources of information, including the clearances and the Mode S DAP. The requirement has been validated in EXE-04.07.02-VP-741.
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

847 848

[RFQ Trace]

[INE G Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<enabler></enabler>	ER_ATC_91	<full></full>
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<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<allocated_to></allocated_to>	<project></project>	10.04.02	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A

849 850 851

[REQ]	
Identifier	REQ-10.04.02-TS-0003.0480
Requirement	The CWP shall display a deviation between cleared IAS and detected IAS.
Title	Display of a warning if deviations between cleared IAS and detected IAS
Status	<in progress=""></in>
Rationale	Actual IAS will be provided by aircraft via ADS. Related to REQ-10.04.02-TS-0001.0430 Implementation not requested in any validation exercise supported by

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	P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

852 853

IREQ Tracel

[]			
Relationship	Linked Element Type	Identifier	Compliance
<satisfies></satisfies>	<enabler></enabler>	APP ATC 94	<full></full>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-OSED-MCMO.2022	<partial></partial>
<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<changed_because_of></changed_because_of>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A

854 855

[REQ]	
Identifier	REQ-10.04.02-TS-0003.0490
Requirement	The CWP shall display warning indicating minutes and Flight ID when there is a deviation between the future positions and the reference trajectory
Title	Display of a warning if deviations between the future positions and the reference trajectory
Status	<in progress=""></in>
Rationale	It is expected that the conformance monitoring tool does not just compare present position against reference trajectory, but also future positions Related to REQ-10.04.02-TS-0001.0460 Implementation not requested in any validation exercise supported by P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""> <real simulation="" time=""></real></live>
Verification Method	<test></test>

856 857

IREQ Tracel

[INEW Hace]			
Relationship	Linked Element Type	Identifier	Compliance
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<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-OSED-MCMO.2025	<partial></partial>
<satisfies></satisfies>	<atms requirement=""></atms>	REQ-05.07.02-OSED-MCMO.2021	<full></full>
<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.01	N/A
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<allocated to=""></allocated>	<project></project>	10.04.02	N/A

858 859

[RFO]

[KEQ]	
Identifier	REQ-10.04.02-TS-0003.0500
Requirement	The CWP shall display a warning when a CTA vs RTA deviation is detected
Title	Display of CTA vs RTA deviation warning
Status	<in progress=""></in>
Rationale	The non-conformance warning is to be distributed, displayed and removed to the interested position sector. Related to REQ-10.04.02-TS-0003.0240 Implementation not requested in any validation exercise supported by P10.04.02
Category	<hmi></hmi>
Validation Method	<live trial=""></live>
	<real simulation="" time=""></real>
Verification Method	<test></test>

860 861

[REQ Trace]

[,]			
Relationship	Linked Element Type	Identifier	Compliance
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Project ID 10.04.02

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<allocated to=""></allocated>	<functional block=""></functional>	Controller HMI Management	N/A
<applies to=""></applies>	<operational area="" focus=""></operational>	OFA03.03.02	N/A
<changed_because_of></changed_because_of>	<change order=""></change>	Change reference	N/A
<allocated to=""></allocated>	<project></project>	10.04.02	N/A



4 References 862 863 [1] Template Toolbox 03.00.00 https://extranet.sesarju.eu/Programme%20Library/SESAR%20Template%20Toolbox.dot 864 [2] Requirements and V&V Guidelines 03.00.00 865 866 https://extranet.sesarju.eu/Programme%20Library/Requirements%20and%20VV%20Guidelin es.doc 867 [3] Templates and Toolbox User Manual 03.00.00 868 https://extranet.sesarju.eu/Programme%20Library/Templates%20and%20Toolbox%20User% 869 870 20Manual.doc 871 [4] B.01.D84 - Integrated Roadmap DS16 Release Note, 00.01.00, 25/05/2016 872 [5] P10.04.02-D08, Conformance Monitoring System Requirements Phase 3, Edition 00.01.00 873 [6] P10.01.07-D120, Technical Architecture Description - Cycle 2015, Edition 00.01.00 [7] P04.07.02-D23, Final MTCD/TCT Safety and Performance Requirements_4, Edition 874 00.03.04 875 876 [8] P04.07.02-D28, OSED 4, Edition 00.04.00 877 [9] P04.07.02-D37, Free Route Operational Service and Environment Definition (OSED) for Step 878 1 - Iteration 2, Edition 00.02.00 [10]P04.07.02-D63, Free Route Safety and Performance Requirements (SPR) for Step 1, Edition 879 880 00.00.06 [11]P05.07.02-D77, Preliminary V2 OSED for Step 1, Edition 00.01.00 881 882 [12] P05.07.02-D78, Preliminary (V2) SPR for Step 1, Edition 00.01.00 883 [13] P05.07.02-D79, Preliminary (V2) INTEROP for Step 1, Edition 00.01.00 4.1 Use of copyright / patent material /classified material 884 885 No copyright material is being used as part of this specification. 4.1.1 Classified Material 886

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No classified material is being used as part of this specification.

Appendix A Traceability of TS requirements with P04.07.02 OSED/SPR and P05.07.02 OSED/SPR/INTEROP

The following table depicts the traceability of TS requirements with P04.07.02 OSED (D28), P04.07.02 SPR (D23) and P05.07.02 OSED/SPR/INTEROP (D77,D78, D79). See References section for references details.

TS Requirement			Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
REQ- 10.04.02- TS- 0001.0010	Eligibility conformance monitoring	or MONA	REQ-04.07.02- OSED-0001.2005 REQ-04.07.02- SPR-CDR1.1200 REQ-05.07.02- OSED-MCMO.2003 REQ-05.07.02- OSED-MCMO.2010 REQ-05.07.02- OSED-MCMO.2010 REQ-05.07.02- OSED-MCMO.2011 REQ-05.07.02- SPR-CDR2.1020 REQ-05.07.02- SPR-CDR2.1020	Monitor input data Continuous monitoring CMON — Reference trajectory CMON — last clearance is part of reference trajectory CMON — direct to IAF—MSA CMON — ADS-B/C data CMON — SID below 120 m above DER—no notification Tactical Trajectory Deviation detects deviations Eligible FPs for CMON tool MONA in Free Routing Airspace Trajectory adherence monitoring in FRA

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890 891 892



TS Requirement		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-04.07.02- OSED-FR04.0250	Maximum frequency of occurrence of loss of route adherence monitoring tool in FRA
			REQ-04.07.02- SPR-FRTA.0101	Continuity of MONA tool for trajectory adherence monitoring in FRA
			REQ-04.07.02- SPR-FR00.0312	Maximum frequency of occurrence of a loss of route adherence monitoring tool in direct routing environment
			REQ-04.07.02- SPR-FRTA.1002	
			REQ-04.07.02- SPR-DR00.0310	
REQ- 10.04.02-	Continuous monitoring of	MONA	REQ-04.07.02- OSED-0001.2005	Monitor input data
TS-	track data and clearance data		REQ-04.07.02-	Continuous monitoring
			SPR-CDR1.1200 REQ-05.07.02-	CMON – Radar data primary source
			OSED-MCMO.2001	CMON – Reference trajectory
			REQ-05.07.02- OSED-MCMO.2003	CMON – last clearance is part of

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TS Requirement			Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
			REQ-05.07.02- OSED-MCMO.2004	reference trajectory CMON – ADS-B/C data	
			REQ-05.07.02- OSED-MCMO.2002	Tactical Trajectory Deviation detects deviations	
			REQ-05.07.02- SPR-CDR2.1020	MONA in Free Routing Airspace	
				Trajectory adherence monitoring in FRA	
			REQ-04.07.02- OSED-FR04.0250		
			REQ-04.07.02- SPR-FRTA.0101	Continuity of MONA tool for trajectory adherence monitoring in FRA	
			REQ-04.07.02- SPR-FRTA.1002		
REQ- 10.04.02- TS-	Conformance monitoring discarding due to	MONA	REQ-04.07.02- OSED-0001.4037	Discard a route deviation	
0001.0023	NoTT deviation detection		REQ-04.07.02- OSED-0001.2004	Conditions for a lateral Deviation	
REQ- 10.04.02- TS- 0001.0024	Vertical deviation when AFL is lower than the vertical constraint	MONA	REQ-05.07.02- OSED-MCMO.2010	CMON – direct to IAF - MSA	





TS Requirement			Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
REQ- 10.04.02- TS- 0001.0026	Conformance Monitoring at or below 120 meters above DER	MONA	REQ-05.07.02- OSED-MCMO.2011	CMON – SID below 120 m above DER – no notification
REQ- 10.04.02- TS- 0001.0027	Conformance Monitoring warnings according to a	MONA	REQ-05.07.02- OSED-MCMO.2012	CMON – SID 120 m above DER below MSA . at
	dedicated vertical tolerance		REQ-05.07.02- OSED-MCMO.2013	CMON – SID 120 m above DER below MSA . at or above
			REQ-05.07.02- OSED-MCMO.2014	CMON – SID 120 m above DER below MSA . at or below
				CMON – SID above MSA . at
			REQ-05.07.02-	CMON – SID above MSA . at or above
			OSED-MCMO.2015 REQ-05.07.02-	CMON – SID above MSA . at or above
			OSED-MCMO.2016	
			REQ-05.07.02- OSED-MCMO.2017	
REQ- 10.04.02- TS- 0001.0030	Route Deviation Detection for a flight plan	MONA	REQ-04.07.02- OSED-0001.3020	Detection of a route deviation
			REQ-04.07.02- SPR-CDR1.1200	Continuous monitoring
			REQ-05.07.02- OSED-MCMO.2005	CMON – Lateral deviation notification
				Conditions for a lateral Deviation
			REQ-04.07.02- OSED-0001.2004	

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TS Requirement		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-04.07.02- OSED-FR04.0250	MONA in Free Routing Airspace Trajectory adherence monitoring in FRA
			REQ-04.07.02- SPR-FRTA.0101	Maximum frequency of occurrence of loss of route adherence monitoring tool in FRA
			REQ-04.07.02- SPR-FR00.0312	Maximum frequency of occurrence of a loss of route adherence monitoring tool in direct routing environment
			REQ-04.07.02- SPR-DR00.0310	
REQ- 10.04.02- TS- 0001.0050	Removal of lateral deviation warning after new route assigned from the controller	MONA	REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- OSED-MCMO.2005	Remove deviation tag CMON – Lateral deviation notification
			REQ-04.07.02- OSED-FR04.0250	MONA in Free Routing Airspace Trajectory adherence monitoring in FRA
			REQ-04.07.02-	

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TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			SPR-FRTA.0101	
REQ- 10.04.02- TS- 0001.0051	Route Deviation Removal	MONA	REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- OSED-MCMO.2005	Remove deviation tag CMON – Lateral deviation notification Conditions for a lateral Deviation
			REQ-04.07.02- OSED-0001.2004	MONA in Free Routing Airspace
			REQ-04.07.02- OSED-FR04.0250	Trajectory adherence monitoring in FRA
			REQ-04.07.02- SPR-FRTA.0101	Maximum frequency of occurrence of loss of route adherence monitoring tool in FRA
			REQ-04.07.02- SPR-FR00.0312	Continuity of MONA tool for trajectory adherence monitoring in FRA Maximum frequency of occurrence of a loss of route adherence monitoring tool in direct routing environment
			REQ-04.07.02- SPR-FRTA.1002	





TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-04.07.02- SPR-DR00.0310	
REQ- 10.04.02- TS- 0001.0450	Lateral tolerance considering PBN	MONA	REQ-05.07.02- OSED-MCMO.2018	CMON –lateral 2 sigma
0001.0430			REQ-05.07.02- OSED-MCMO.2024	CMON – Lateral tolerance considering PBN
REQ- 10.04.02- TS-	Vertical Rate Deviation Detection	MONA	REQ-04.07.02- OSED-0001.3021	Detection of a cleared rate deviation
0001.0141			REQ-05.07.02- OSED-MCMO.2006	CMON – vertical deviation notification
				Conditions for a vertical Deviation
			REQ-04.07.02- OSED-0001.3126	
REQ- 10.04.02- TS- 0001.0142	Vertical Rate Deviation removal due to flight.	MONA	REQ-04.07.02- SPR-CDR1.1210	Remove deviation tag CMON – vertical
0001.0142			REQ-05.07.02- OSED-MCMO.2006	deviation notification Conditions for a vertical Deviation
			REQ-04.07.02- OSED-0001.3126	
REQ- 10.04.02- TS-	CFL Deviation Detection for CFL Reached	MONA	REQ-04.07.02- OSED-0001.3022	Detection of a CFL deviation
0001.0151			REQ-05.07.02- OSED-MCMO.2006	CMON – vertical deviation notification
			REQ-04.07.02- OSED-0001.3126	Conditions for a vertical Deviation
REQ- 10.04.02- TS-	CFL Deviation Detection for CFL Not Reached	MONA	REQ-04.07.02- OSED-0001.3022	Detection of a CFL deviation
0001.0152			REQ-05.07.02- OSED-MCMO.2006	CMON – vertical deviation notification





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TS Requirement			Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-04.07.02- OSED-0001.3126	Conditions for a vertical Deviation
REQ- 10.04.02- TS- 0001.0153	CFL Deviation removal due to flight return to cleared level.	MONA	REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- OSED-MCMO.2006 REQ-04.07.02- OSED-0001.3126	Remove deviation tag CMON – vertical deviation notification Conditions for a vertical Deviation
REQ- 10.04.02- TS- 0001.0161	Mode S Selected Altitude Deviation Detection with clearance latency	MONA	REQ-04.07.02- OSED-0001.3026 REQ-04.07.02- SPR-CDR1.1220	Adherence of downlink parameters to clearances Mode S parameters
REQ- 10.04.02- TS- 0001.0163	Mode S Selected Altitude Deviation removal	MONA	REQ-04.07.02- OSED-0001.3026 REQ-04.07.02- SPR-CDR1.1210	Adherence of downlink parameters to clearances Remove deviation tag
REQ- 10.04.02- TS- 0001.0165	Mode S Selected Altitude Deviation Detection with pilot latency.	MONA	REQ-04.07.02- OSED-0001.3026 REQ-04.07.02- SPR-CDR1.1220	Adherence of downlink parameters to clearances Mode S parameters
REQ- 10.04.02- TS- 0001.0181	Level Bust Deviation Detection	MONA	REQ-04.07.02- OSED-0001.3023 REQ-05.07.02- OSED-MCMO.2006 REQ-04.07.02- OSED-0001.3126	Detection of a Level Bust CMON – vertical deviation notification Conditions for a vertical Deviation
REQ- 10.04.02- TS-	Level Bust Deviation removal due to vertical	MONA	REQ-04.07.02- SPR-CDR1.1210	Remove deviation tag CMON – vertical





TS Requirem	ent		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
0001.0182	rate correction.		REQ-05.07.02- OSED-MCMO.2006 REQ-04.07.02- OSED-0001.3126	deviation notification Conditions for a vertical Deviation	
REQ- 10.04.02- TS- 0001.0191	NoTT Deviation Detection	MONA	REQ-04.07.02- OSED-0001.3024 REQ-04.07.02- OSED-0001.2004	Detection of unavailability of a Flight Plan Conditions for a lateral Deviation	
REQ- 10.04.02- TS- 0001.0194	NoTT Deviation removal	MONA	REQ-04.07.02- SPR-CDR1.1210	Remove deviation tag	
REQ- 10.04.02- TS- 0001.0170	Coordination conditions failure warning	MONA	REQ-04.07.02- OSED-0002.4017 REQ-04.07.02- OSED-0002.3053	Detection of deviations from entry/exit conditions Monitoring of deviations wrt the entry/exit conditions	
			REQ-04.07.02- SPR-CDR2.1240 REQ-04.07.02- OSED-0002.2014	Deviating from the flight level constraint Monitoring of achievable entry/exit conditions	
REQ- 10.04.02- TS- 0001.0175	Entry/Exit coordination failure	MONA/HMI	REQ-04.07.02- OSED-0002.4017	Detection of deviations from entry/exit conditions	
0001.0110			REQ-04.07.02- OSED-0002.3053	Monitoring of deviations wrt the entry/exit conditions	
			REQ-04.07.02- SPR-CDR2.1240	Deviating from the flight level constraint	
			REQ-04.07.02- SPR-CDR2.1250	Spurious alerts Monitoring of	





TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-04.07.02- OSED-0002.2014	achievable entry/exit conditions
REQ- 10.04.02- TS- 0001.0400	STAR constraint at or above	MONA	REQ-05.07.02- OSED-MCMO.2007 REQ-05.07.02- OSED-MCMO.2008 REQ-05.07.02- OSED-MCMO.2009	CMON – STAR constraint at or above CMON – STAR constraint at CMON – STAR constraint at or below
REQ- 10.04.02- TS- 0001.0410	CTA vs RTA deviation	MONA	REQ-05.07.02- OSED-MCMO.2019 REQ-05.07.02- OSED-MCMO.2020 REQ-04.07.02- OSED-0003.2031	CMON – CTA vs RTA deviation CMON – time tolerance Warning on false CTO implementation
REQ- 10.04.02- TS- 0001.0430	Actual IAS vs Cleared IAS deviation	MONA	REQ-05.07.02- OSED-MCMO.2022	CMON – Actual IAS vs Cleared IAS deviation
REQ- 10.04.02- TS- 0001.0460	Aircraft Derived Data or EPP usage	MONA	REQ-05.07.02- OSED-MCMO.2025 REQ-05.07.02- OSED-MCMO.2021	CMON – Aircraft Derived Data or EPP usage CMON – ATA vs ETA deviation
REQ- 10.04.02- TS- 0001.0470	Conformance monitoring capacity	MONA	REQ-05.07.02- SPR-CDR1.3020	Minimum flight plans
REQ- 10.04.02- TS- 0001.0320	Processing of track information	MONA	REQ-04.07.02- OSED-0001.2005 REQ-05.07.02- OSED-MCMO.2001 REQ-05.07.02- INTEROP- 0030.0001 REQ-05.07.02- INTEROP- 0030.0006	Monitor input data CMON – Radar data primary source Eligible FPs for CMON tool Interoperability of Conformance Monitoring with Surveillance data Interoperability of





TS Requirem	ent		Related requirement	
13 Requirem	10 Requirement		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-05.07.02- INTEROP- 0030.0007	Conformance Monitoring with data entered by the ATC Operational Supervisor
REQ- 10.04.02- TS- 0001.0330	Data items from a non-conformance warning	MONA	REQ-04.07.02- SPR-CDR1.1190 REQ-05.07.02- SPR-CDR2.1150 REQ-05.07.02- INTEROP- 0030.0002	HMI alert Tactical Trajectory Deviation provides details about deviation Interoperability between Conformance Monitoring & the Controller. Interoperability between Conformance Monitoring & the Trajectory Prediction Service (Deviation Trajectory Request)
			REQ-05.07.02- INTEROP- 0030.0003	



TS Requirem	ent		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
REQ- 10.04.02- TS- 0001.0340	Conditions for Deviation Trajectory calculation trigger	MONA	REQ-04.07.02- OSED-0001.2004 REQ-04.07.02- OSED-0001.3010 REQ-04.07.02- OSED-0001.3011 REQ-04.07.02- SPR-CDR1.1120 REQ-04.07.02- SPR-CDR1.1140 REQ-04.07.02- SPR-CDR1.1150 REQ-04.07.02- SPR-CDR1.1150 REQ-04.07.02- SPR-CDR1.1160 REQ-04.07.02- SPR-CDR1.1170 REQ-04.07.02- SPR-CDR1.1170	Conditions for a Deviation Trajectory Predict the lateral trajectory after a lateral deviation Predict the vertical trajectory after a rate deviation Route deviation CFL deviation Speed deviation Speed deviation No valid flight plan data Tactical Trajectory Deviation provides details about deviation Alternative Trajectory Assessment info from Trajectory Deviation Interoperability between Conformance Monitoring & the Trajectory Prediction Service (Deviation Trajectory Request)	
			REQ-05.07.02- SPR-CDR2.1160		





TS Requirem	ent		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
			REQ-05.07.02- INTEROP- 0030.0003		
REQ- 10.04.02- TS- 0001.0341	Tactical Trajectory Calculation Trigger due to absence of deviation	MONA	REQ-04.07.02- OSED-0001.3093 REQ-04.07.02- SPR-CDR1.1180	Conditions to predict the lateral trajectory Tactical and deviation trajectories Alternative Trajectory	
REQ-	Threshold inputs.	MONA	REQ-05.07.02- SPR-CDR2.1160 REQ-04.07.02-	Assessment info from Trajectory Deviation Detection of a route	
10.04.02- TS- 0001.0350			OSED-0001.3020 REQ-04.07.02- OSED-0001.3021	deviation Detection of a cleared rate deviation	
REQ- 10.04.02- TS-	Processing of planned trajectory and controller	MONA	REQ-04.07.02- OSED-0001.2005	Monitor input data	
0001.0310	clearances data		REQ-04.07.02- SPR-CDR1.1200	Continuous monitoring	
			REQ-05.07.02- SPR-CDR2.1140	CMON – last clearance is part of	
			REQ-05.07.02- OSED-MCMO.2004	reference trajectory CMON – Path	
			REQ-05.07.02- OSED-MCMO.2023	terminators compatibility	
			REQ-05.07.02- SPR-CDR2.1140	Tactical Trajectory Deviation updated with new trajectory	
			REQ-05.07.02- INTEROP- 0030.0001	Eligible FPs for CMON tool Interoperability	
founding members			REQ-05.07.02-	between Conformance	





TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			INTEROP- 0030.0004 REQ-05.07.02- INTEROP- 0030.0005	Monitoring & the Trajectory Prediction Service (Trajectory Data) Interoperability of Conformance Monitoring with Flight Data
REQ- 10.04.02- TS- 0001.0360	Acknowledgement inputs.	MONA/HMI	REQ-05.07.02- INTEROP- 0030.0005	Interoperability of Conformance Monitoring with Flight Data
REQ- 10.04.02- TS- 0001.0180	Displaying availability of non- conformance warnings.	MONA/HMI	REQ-04.07.02- OSED-0001.3019 REQ-04.07.02- SPR-CDR1.1190 REQ-05.07.02- OSED-MCMO.2005 REQ-05.07.02- OSED-MCMO.2006	Conditions for displaying a deviation warning HMI alert CMON – Lateral deviation notification CMON – vertical deviation notification
REQ- 10.04.02- TS- 0001.0190	Availability of type of trajectory deviation for non-conformance warning.	MONA/HMI	OSED-0001.3019 REQ-04.07.02- SPR-CDR1.1190	Conditions for displaying a deviation warning HMI alert
REQ- 10.04.02- TS- 0001.0230	Presentation and removal of conformance warning	MONA/HMI	REQ-04.07.02- OSED-0001.3019 REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- OSED-MCMO.2005 REQ-05.07.02- OSED-MCMO.2006	Conditions for displaying a deviation warning Remove deviation tag CMON – Lateral deviation notification CMON – vertical deviation notification





TS Requireme	TS Requirement		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
REQ- 10.04.02- TS- 0003.0240	Presentation of CTA vs RTA deviation	MONA	REQ-05.07.02- OSED-MCMO.2019 REQ-04.07.02- OSED-0003.2031	CMON – CTA vs RTA deviation Warning on false CTO implementation	
REQ- 10.04.02- TS- 0002.0100	Acceptability of Loss of TC-Aid	MONA	REQ-04.07.02- SPR-CDR1.2030	Loss of TC Aid	
REQ- 10.04.02- TS- 0002.0200	Acceptability of Delay of TC-Aid	MONA	REQ-04.07.02- SPR-CDR1.2070	Delay of TC Aid	
REQ- 10.04.02- TS- 0002.0300	Acceptability of Corruption (Undetected) of TC-Aid	MONA	REQ-04.07.02- SPR-CDR1.2110	Corruption of TC Aid	
REQ- 10.04.02- TS- 0002.0400	Acceptability of Corruption (Detected) of TC- Aid	MONA	REQ-04.07.02- SPR-CDR1.2140	Corruption of TC Aid	
REQ- 10.04.02- TS- 0002.0240 (10.10.02 contribution)	Controller removing the lateral deviation warning when assessed.	MONA/HMI	REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- SPR-CDR2.1140	Remove deviation tag Tactical Trajectory Deviation updated with new trajectory Tactical Trajectory Deviation provides details about deviation Interoperability of	
			REQ-05.07.02- SPR-CDR2.1150	Conformance Monitoring with Flight Data	
			REQ-05.07.02- INTEROP- 0030.0005		
REQ- 10.04.02- TS- 0002.0250 (10.10.02	Display of an Entry/Exit coordination failure	MONA/HMI	REQ-04.07.02- OSED-0002.4017	Detection of deviations from entry/exit conditions Monitoring of	
contribution)			REQ-04.07.02-	deviations wrt the entry/exit conditions	





TS Requirem	ent		Related requirement		
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title	
			OSED-0002.3053 REQ-04.07.02- SPR-CDR2.1240 REQ-04.07.02- SPR-CDR2.1250 REQ-05.07.02- SPR-CDR2.1150 REQ-04.07.02- OSED-0002.2014	Deviating from the flight level constraint Spurious alerts Tactical Trajectory Deviation provides details about deviation Monitoring of achievable entry/exit conditions	
REQ- 10.04.02- TS- 0002.0260 (10.10.02 contribution)	Controller acknowledge to deviations	MONA/HMI	REQ-05.07.02- INTEROP- 0030.0005	Interoperability of Conformance Monitoring with Flight Data	
REQ- 10.04.02- TS- 0002.0270 (10.10.02 contribution)	Display of the non-conformance warnings due to deviations	MONA/HMI	REQ-04.07.02- OSED-0001.3019 REQ-04.07.02- SPR-CDR1.1190 REQ-05.07.02- SPR-CDR2.1030 REQ-05.07.02- INTEROP- 0030.0002	Conditions for displaying a deviation warning HMI alert Tactical Trajectory Deviation shows deviation alerts Interoperability between Conformance Monitoring & the Controller.	
REQ- 10.04.02- TS- 0002.0280	Display of the type of deviation in a non-conformance	MONA/HMI	REQ-04.07.02- OSED-0001.3019	Conditions for displaying a deviation warning	





TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
(10.10.02 contribution)	warning		REQ-04.07.02- SPR-CDR1.1190 REQ-05.07.02- SPR-CDR2.1030 REQ-05.07.02- INTEROP- 0030.0002	HMI alert Tactical Trajectory Deviation shows deviation alerts Interoperability between Conformance Monitoring & the Controller.
REQ- 10.04.02- TS- 0002.0290 (10.10.02 contribution)	Display and remove the monitoring warning.	MONA/HMI	REQ-04.07.02- OSED-0001.3019 REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- SPR-CDR2.1030 REQ-05.07.02- INTEROP- 0030.0002	Conditions for displaying a deviation warning Remove deviation tag Tactical Trajectory Deviation shows deviation alerts Interoperability between Conformance Monitoring & the Controller.
REQ- 10.04.02- TS- 0002.0310 (10.10.02 contribution)	Display of a warning if the TC- Aid detects deviations	MONA/HMI	REQ-04.07.02- SPR-CDR1.1190 REQ-05.07.02- SPR-CDR2.1030 REQ-05.07.02- INTEROP- 0030.0002	HMI alert Tactical Trajectory Deviation shows deviation alerts Interoperability between Conformance Monitoring & the Controller.
REQ- 10.04.02- TS- 0002.0320 (10.10.02 contribution)	Removal of the warning in case of a deviation no longer exists	MONA/HMI	REQ-04.07.02- SPR-CDR1.1210 REQ-05.07.02- SPR-CDR2.1030	Remove deviation tag Tactical Trajectory Deviation shows deviation alerts Interoperability between Conformance Monitoring & the Controller.



TS Requirem	ent		Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
			REQ-05.07.02- INTEROP- 0030.0002	
REQ- 10.04.02- TS- 0002.0350 (10.10.02 contribution)	Display deviations between actual track and controller clearance.	MONA/HMI	REQ-05.07.02- INTEROP- 0030.0003	Interoperability between Conformance Monitoring & the Trajectory Prediction Service (Deviation Trajectory Request)
REQ- 10.04.02- TS- 0002.0360	Display of deviation warnings based on frequency and	MONA/HMI	REQ-04.07.02- OSED-0001.3019	Conditions for displaying a deviation warning
(10.10.02 contribution)	actual position		REQ-05.07.02- SPR-CDR2.1040	Tactical Trajectory Deviation Detection notifies only certain deviations
			REQ-05.07.02- SPR-CDR2.1090	Tactical Trajectory Deviation reflects sectors
REQ- 10.04.02- TS- 0002.0370	Display of a warning when PC- Aid detects deviations from	MONA/HMI	REQ-04.07.02- OSED-0002.4017 REQ-04.07.02-	Detection of deviations from entry/exit conditions Deviating from the
(10.10.02 contribution)	coordination.		SPR-CDR2.1240 REQ-04.07.02-	flight level constraint Spurious alerts
REQ- 10.04.02- TS- 0002.0380 (10.10.02 contribution)	Display of a warning if deviations between clearance and received Mode S DAP	MONA/HMI	SPR-CDR2.1250 REQ-04.07.02- OSED-0001.3026	Adherence of downlink parameters to clearances
REQ- 10.04.02- TS- 0002.0390 (10.10.02 contribution)	Display of a warning if deviations between new clearance and Mode S DAP	MONA/HMI	REQ-04.07.02- OSED-0001.3026	Adherence of downlink parameters to clearances
REQ- 10.04.02- TS- 0003.0480 (10.10.02 contribution)	Display of a warning if deviations between cleared IAS and detected IAS	MONA/HMI	REQ-05.07.02- OSED-MCMO.2022	CMON – Actual IAS vs Cleared IAS deviation





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TS Requirement			Related requirement	
Identifier	Title	Subsystem element that the requirement is allocated to	Identifier	Title
REQ- 10.04.02- TS- 0003.0490 (10.10.02 contribution)	Display of a warning if deviations between the future positions and the reference trajectory	MONA/HMI	REQ-05.07.02- OSED-MCMO.2025 REQ-05.07.02- OSED-MCMO.2021	CMON – Aircraft Derived Data or EPP usage CMON – ATA vs ETA deviation
REQ- 10.04.02- TS- 0003.0500 (10.10.02 contribution)	Display of CTA vs RTA deviation warning	MONA/HMI	REQ-05.07.02- OSED-MCMO.2019	CMON – CTA vs RTA deviation
REQ- 10.04.02- TS- 0002.0500	Frequency of detected corruption of input data	MONA	REQ-05.07.02- SPR-CDR1.2030 REQ-05.07.02- SPR-CDR1.2080	Detected corruption of the new trajectory Corrupted data in the deviation trajectory function
REQ- 10.04.02- TS- 0002.0600	Frequency of undetected corruption of input data	MONA	REQ-05.07.02- SPR-CDR1.2030 REQ-05.07.02- SPR-CDR1.2080	Detected corruption of the new trajectory Corrupted data in the deviation trajectory function

Table 4: TS requirements traceability

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Appendix B Subset of TS requirements linked to HMI functional block

The following table depicts a subset of TS requirements linked to HMI functional block.

	Title	TS requirements written
Identifier		in close collaboration with P10.10.02 project
REQ-10.04.02-TS-0001.0175	•	No
	Acknowledgement inputs.	No
REQ-10.04.02-TS-0001.0180	Displaying availability of non-conformance warnings.	No
REQ-10.04.02-TS-0001.0190	Availability of type of trajectory deviation for non-conformance warning.	No
REQ-10.04.02-TS-0001.0230	Presentation and removal of conformance warning	No
REQ-10.04.02-TS-0002.0240	Controller removing the lateral deviation warning when assessed.	Yes
REQ-10.04.02-TS-0002.0250	Display of an Entry/Exit coordination failure	Yes
REQ-10.04.02-TS-0002.0260	Controller acknowledge to deviations	Yes
REQ-10.04.02-TS-0002.0270	Display of the non-conformance warnings due to deviations	Yes
REQ-10.04.02-TS-0002.0280	Display of the type of deviation in a non- conformance warning	Yes
REQ-10.04.02-TS-0002.0290	Display and remove the monitoring warning.	Yes
	Display of a warning if the TC-Aid detects deviations	Yes
REQ-10.04.02-TS-0002.0320	Removal of the warning in case of a deviation no longer exists	Yes
REQ-10.04.02-TS-0002.0350	Display deviations between actual track and controller clearance.	Yes



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Identifier	Title	TS requirements written in close collaboration with P10.10.02 project
REQ-10.04.02-TS-0002.0360	Display of deviation warnings based on frequency and actual position	Yes
REQ-10.04.02-TS-0002.0370	Display of a warning when PC-Aid detects deviations from coordination	Yes
REQ-10.04.02-TS-0002.0380	Display of a warning if deviations between clearance and received Mode S DAP	Yes
REQ-10.04.02-TS-0002.0390	Display of a warning if deviations between new clearance and Mode S DAP	Yes
REQ-10.04.02-TS-0003.0480	Display of a warning if deviations between cleared IAS and detected IAS	Yes
REQ-10.04.02-TS-0003.0490	Display of a warning if deviations between the future positions and the reference trajectory	Yes
REQ-10.04.02-TS-0003.0500	Display of CTA vs RTA deviation warning	Yes

Table 5: Subset of TS requirements linked to HMI functional block

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Appendix C Subset of 04.07.02 OSED and SPR allocated to Functional Block MONA by P10.01.07

Subset of P04.07.02 OSED (D28) and SPR (D23) allocated to Functional Block MONA by P10.01.07 on D120 [6].

OSED Deliverable	OSED Requirement Identifier	OSED Requirement Title	OSED Requirement Text	Functional Block
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.2005	Monitor input data	The "TC aid" shall continuously monitor actual track data and controller clearance data.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3019	Conditions for displaying a deviation warning	The deviation warnings shall be displayed for aircraft depending on sector frequency status and actual position.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3020	Detection of a route deviation	The "TC aid" shall detect route deviations a) if the actual track position differs from the cleared flight path by more than a parameter, or b) if the actual track position is outside a radius around a waypoint.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3021	Detection of a cleared rate deviation	The "TC-aid" shall detect vertical rate deviations if a) no CFL deviation or a level bust is detected at the same time, and b) vertical latency time after a new vertical clearance has been entered, and c) the difference between AFL and CFL exceeds a threshold, and d) no minimum actual rate is detected into the direction of the CFL or the actual rate differs from the cleared vertical rate by more than a parameter	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3022	Detection of a CFL deviation	The "TC aid" shall detect a Cleared Flight Level (CFL) deviation if the difference between AFL and CFL exceeds a threshold.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3023	Detection of a Level Bust	The "TC aid" shall detect a Level Bust if the actual vertical rate for climb and/or descent close to the CFL exceeds a threshold.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3024	Detection of unavailability of a Flight Plan	The "TC aid" shall detect a NoTT deviation if a) no valid flight plan data (route information) is available for a flight; b) the aircraft is beyond or before its cleared (filed) route.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.4037	Discard a route deviation	The system shall discard a route deviation if a NoTT status has been detected.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0001.3026	Adherence of downlink parameters to clearances	The "TC aid" shall detect deviations between controller clearance data and Mode S DAP.	MONA
04.07.02-OSED- D19-02.00.00- REQ	REQ-04.07.02- OSED- 0002.4017	Detection of deviations from entry/exit conditions	The "PC aid" shall alert the controller to any deviations from coordination conditions.	MONA

Table 6: P04.07.02 OSED allocated to P10.04.02

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906 Subset of P04.07.02 SPR (D23) allocated to Functional Block MONA proposed by P10.04.02 partners and confirmed by P10.01.07 and finally adjusted after deliverable D23.

SPR	SPR	SPR Requirement Text	Functional
Requirement Identifier	Requirement Title		Block
REQ- 04.07.02- SPR- CDR1.1120	Route deviation	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects a Route deviation.	MONA
REQ- 04.07.02- SPR- CDR1.1130	Lateral deviation	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects a Lateral deviation.	MONA
REQ- 04.07.02- SPR- CDR1.1140	Vertical rate deviation	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects a ∀ertical Rate Deviation.	MONA
REQ- 04.07.02- SPR- CDR1.1150	CFL deviation	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects a CFL deviation.	MONA
REQ- 04.07.02- SPR- CDR1.1160	Speed deviation	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects a Speed Deviation.	MONA
REQ- 04.07.02- SPR- CDR1.1170	No valid flight plan data	The TC Aid shall create a deviation trajectory if Flight Path Monitoring detects that there is no valid flight plan data available.	MONA
REQ- 04.07.02- SPR- CDR1.1180	Tactical and deviation trajectories	The calculated trajectory shall be a Tactical Trajectory if valid flight plan data is available and if no deviation, as detected by Flight Path Monitoring occurred. Otherwise it is referred to as a deviation trajectory.	MONA
REQ- 04.07.02- SPR- CDR1.1190	HMI alert	The TC Aid shall alert the controller to any deviations via HMI on the radar display.	MONA
REQ- 04.07.02- SPR- CDR1.1200	Continuous monitoring	The TC Aid shall continuously monitor actual track data and controller clearance data.	MONA
REQ- 04.07.02- SPR- CDR1.1210	Remove deviation tag	The TC Aid shall detect if a deviation no longer exists and remove the display of the alert to the controller.	MONA
REQ- 04.07.02- SPR- CDR1.1220	Mode S parameters	The TC Aid shall detect deviations between controller clearance data and Mode S downlinked airborne parameters.	MONA
REQ- 04.07.02- SPR- CDR1.2030	Loss of TC Aid	The probability of Loss of TC Aid shall be no more than 3.33E-07 per flight hour.	MONA
REQ- 04.07.02- SPR- CDR1.2070	Delay of TC Aid	The probability of Delay of the TC Aid shall be no more than 3.33E-07 per flight hour.	MONA
REQ- 04.07.02- SPR- CDR1.2110	Corruption of TC Aid (undetected)	The probability of Corruption (undetected) of the TC Aid shall be no more than 3.33E-07 per flight hour.	MONA



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SPR Requirement Identifier	SPR Requirement Title	SPR Requirement Text	Functional Block
REQ- 04.07.02- SPR- CDR1.2140	Corruption of TC Aid (detected)	The probability of Corruption (Detected) of the TC Aid shall be no more than 1.00E-05 per flight hour.	MONA
REQ- 04.07.02- SPR- CDR2.1240	Deviating from the flight level constraint	The PC Aid shall alert the controller if the flight is deviating from the applied coordination constraints.	MONA
REQ- 04.07.02- SPR- CDR2.1250	Spurious alerts	The deviation alerts associated with coordination constraints shall be triggered at times/events appropriate to the controller role.	MONA

Table 7: P04.07.02 SPR allocated to P10.04.02





Appendix D Subset of P05.07.02 OSED, SPR and INTEROP allocated to Functional Block MONA by P10.04.02 partners

Subset of P05.07.02 D77 Preliminary V2 OSED for Step 1 allocated to Functional Block MONA assumed by P10.04.02 partners .

OSED Identifier	OSED Title	OSED Requirement	Functional Block
REQ-05.07.02- OSED- MCMO.2001	CMON – Radar data primary source	Radar data shall be the primary source of information for obtaining aircraft current position for conformance monitoring purposes	MONA
REQ-05.07.02- OSED- MCMO.2003	CMON – Reference trajectory	For conformance monitoring purposes, the reference trajectory shall be the ground predicted trajectory	MONA
REQ-05.07.02- OSED- MCMO.2004	CMON – last clearance is part of reference trajectory	For conformance monitoring purposes, the ground predicted trajectory shall be updated continuously with the last clearance/instruction provided by ATC.	MONA
REQ-05.07.02- OSED- MCMO.2005	CMON – Lateral deviation notification	Conformance monitoring tool shall provide a lighting warning on the CWP when an aircraft is deviating its lateral navigation regarding ground predicted trajectory	MONA
REQ-05.07.02- OSED- MCMO.2006	CMON – vertical deviation notification	Conformance monitoring tool shall provide a lighting warning on the CWP when an aircraft does not meet the required vertical constraint regarding ground predicted trajectory	MONA
REQ-05.07.02- OSED- MCMO.2007	CMON – STAR constraint at or above	Flying a STAR, for conformance monitoring purposes, at a waypoint with a vertical constraint of "at or above", the vertical tolerance for providing a warning shall be - 150 ft	MONA
REQ-05.07.02- OSED- MCMO.2008	CMON – STAR constraint at	Flying a STAR, for conformance monitoring purposes, at a Waypoint with a vertical constraint of "at ", the vertical tolerance for providing a warning shall be \pm 150 ft.	MONA
REQ-05.07.02- OSED- MCMO.2009	CMON – STAR constraint at or below	Flying a STAR, for conformance monitoring purposes, at a Waypoint with a vertical constraint of "at or below", the vertical tolerance for providing a warning shall be + 150 ft	MONA
REQ-05.07.02- OSED- MCMO.2010	CMON – direct to IAF - MSA	In arrival, when the aircraft is cleared "direct to IAF" out of a STAR., the vertical tolerance for providing a warning shall be - 150 ft of Minimum Sector Altitude.	MONA
REQ-05.07.02- OSED- MCMO.2011	CMON – SID below 120 m above DER – no notification	Flying a SID, for conformance monitoring purposes, a warning shall not be provided when aircraft is flying at or below 120 m above DER.	MONA



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OSED Identifier	OSED Title	OSED Requirement	Functional Block
REQ-05.07.02- OSED- MCMO.2012	CMON – SID 120 m above DER below MSA . at	Flying a SID, for conformance monitoring purposes, when the aircraft is flying between 120 m height above DER and MSA, at a Waypoint with a vertical constraint of "at", the vertical tolerance for providing a warning shall be ± 100 ft	MONA
REQ-05.07.02- OSED- MCMO.2013	CMON – SID 120 m above DER below MSA . at or above	Flying a SID, for conformance monitoring purposes, when the aircraft is flying between 120 m height above DER and MSA, at a Waypoint with a vertical constraint of "at or above", the vertical tolerance for providing a warning shall be - 100 ft.	MONA
REQ-05.07.02- OSED- MCMO.2014	CMON – SID 120 m above DER below MSA . at or below	Flying a SID, for conformance monitoring purposes, when the aircraft is flying between 120 m height above DER and MSA, at a Waypoint with a vertical constraint of "at or below", the vertical tolerance for providing a warning shall be + 100 ft.	MONA
REQ-05.07.02- OSED- MCMO.2015	CMON – SID above MSA . at	Flying a SID, for conformance monitoring purposes, when the aircraft is flying above MSA, at a Waypoint with a vertical constraint of "at", the vertical tolerance for providing a warning shall be ± 150 ft.	MONA
REQ-05.07.02- OSED- MCMO.2016	CMON – SID above MSA . at or above	Flying a SID, for conformance monitoring purposes, when the aircraft is flying above MSA, at a Waypoint with a vertical constraint of "at or above", the vertical tolerance for providing a warning shall be - 150 ft.	MONA
REQ-05.07.02- OSED- MCMO.2017	CMON – SID above MSA . at or below	Flying a SID, for conformance monitoring purposes, when the aircraft is flying above MSA, at a Waypoint with a vertical constraint of "at or below", the vertical tolerance for providing a warning shall be + 150 ft.	MONA
REQ-05.07.02- OSED- MCMO.2018	CMON –lateral 2 sigma	For conformance monitoring purposes, the lateral tolerance for providing a warning shall be the accuracy of the PBN specification ($\pm 2\sigma$)	MONA
REQ-05.07.02- OSED- MCMO.2019	CMON – CTA vs RTA deviation	Conformance monitoring tool will provide a lighting warning on the CWP when aircraft's CTA does not meet RTA over a particular waypoint	MONA
REQ-05.07.02- OSED- MCMO.2020	CMON – time tolerance	For conformance monitoring purposes, the time tolerance for providing a warning shall be ± X s.	MONA
REQ-05.07.02- OSED- MCMO.2022	CMON – Actual IAS vs Cleared IAS deviation	Conformance monitoring tool shall provide a lighting warning when actual IAS is different to cleared IAS	MONA
REQ-05.07.02- OSED- MCMO.2024	CMON – Lateral tolerance considering PBN	Lateral tolerance which is used for providing a warning by conformance monitoring tool shall be adaptable to PBN specification required for a particular PBN application.	MONA

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OSED Identifier	OSED Title	OSED Requirement	Functional Block
REQ-05.07.02- OSED- MCMO.2025	CMON – Aircraft Derived Data or EPP usage	When the available information from aircraft allows, conformance monitoring tool shall provide a tabular warning indicating "in "xxx" minutes, "Flight ID" shall be deviated from latest clearance.	MONA

Table 8: P05.07.02 OSED allocated to P10.04.02

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Subset of P05.07.02 D78 Preliminary (V2) SPR for Step 1 allocated to Functional Block MONA proposed by P10.04.02 partners.

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SPR Identifier	SPR Title	SPR Requirement	Functional Block
REQ- 05.07.02-PR- xxxxxxxxxxx		Minimum number of Flight Plans shall be 200	MONA
REQ- 05.07.02- SPR- CDR2.1140		The PC Aid shall automatically coordinate flights into the sector without reference to the planner controller when the coordination passes the MTCD check.	MONA
REQ- 05.07.02- SR_Hz27_2		The frequency of occurrence of detected corruption of input data from Trajectory Deviation Detection function shall not be greater than 0.4x10-7(/flt hr)	MONA
REQ- 05.07.02- SR_Hz28_2		The frequency of occurrence of undetected corruption of input data from Trajectory Deviation Detection function shall not be greater than 0.4x10-7(/flt hr)	MONA

Table 9: P05.07.02 SPR allocated to P10.04.02



Requirements traceability to SESAR solution **Appendix E**

Solution	Linked SPR (from P04.07.02 D63, D37)	Linked TS
#32: Free route through the use of direct routing	REQ-04.07.02-SPR-DR00.0310 The frequency of occurrence of a loss of route adherence monitoring tool in direct routing environment shall not be greater than 2.00E-03 per sector operational hour	REQ-10.04.02-TS-0001.0051 REQ-10.04.02-TS-0001.0010 REQ-10.04.02-TS-0001.0030
	REQ-04.07.02-OSED-FR04.0250 In Free Routing Airspace, the ATCOs shall be supported by a MONA tool to monitor the route adherence	REQ-10.04.02-TS-0001.0051 REQ-10.04.02-TS-0001.0010 REQ-10.04.02-TS-0001.0022 REQ-10.04.02-TS-0001.0030 REQ-10.04.02-TS-0001.0050
#33: Free route through free routing for flights both	REQ-04.07.02-SPR-FRTA.0101 In Free Routing Airspace, the ATCOs shall be supported by a MONA tool to monitor the trajectory adherence	REQ-10.04.02-TS-0001.0051 REQ-10.04.02-TS-0001.0010 REQ-10.04.02-TS-0001.0022 REQ-10.04.02-TS-0001.0030 REQ-10.04.02-TS-0001.0050
in cruise and vertically evolving above a specified flight level	REQ-04.07.02-SPR-FR00.0312 The frequency of occurrence of loss of route adherence monitoring tool in FRA shall not be greater than 2.00E-03 per sector operational hour	REQ-10.04.02-TS-0001.0051 REQ-10.04.02-TS-0001.0010 REQ-10.04.02-TS-0001.0030
	REQ-04.07.02-SPR-FRTA.1002 In Free Routing Airspace, the MONA shall permanently and continuously check the flight adherence to the cleared trajectory	REQ-10.04.02-TS-0001.0051 REQ-10.04.02-TS-0001.0010 REQ-10.04.02-TS-0001.0022

Table 10 - Traceability to SESAR solutions #32 and #33

All the other requirements not listed in the table above are linked to the Solution #27 Medium term conflict detection (MTCD) and conformance monitor tools.

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Appendix F Functional improvements on the top of FASTI baseline

Requirements described in this document has as a starting point the FASTI baseline, that was considered at the beginning of the SESAR program the state of the art for the Conformance monitoring functional block.

- A description of the new functionalities and features of SESAR Conformance Monitoring as an improvement compared to FASTI and as contribution to Solution #27 are described in the following:
- **heading monitoring**: monitoring of lateral deviation while a heading clearance is provided; A new Alert **(CHAM)** is provided when the flight is not conforming the issued clearance;
 - **rate monitoring**: rate change, using of actual vertical rates, is taken into account during an evolving phase when an aircraft is about to start its evolution or is about to reach its cleared FL. The main aim is to minimize false alert by getting a more realistic prediction;
 - Potential coordination failure monitoring;
 - Comparison of Mode S DAP with clearance input from controllers;
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 Detection of Level Bust.

Furthermore, the combination and availability of the tactical decision support tools together with the conformance monitoring tool as a unique integrated system can also be considered as an innovation respect to the initial baseline, whose potential in terms of KPA has been validated in the related validation exercises.

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